

Computational Approach to Riemann Surfaces

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with

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Theta-function solutions to the Kadomtsev-Petviashvili equation

- E. D. Belokolos, A. I. Bobenko, V. Z. Enol'skii, A. R. Its, and V. B. Matveev. *Algebro-geometric approach to nonlinear integrable problems*. Springer Series in Nonlinear Dynamics. Springer-Verlag, Berlin, 1994.



$$3u_{yy} + \partial_x(6uu_x + u_{xxx} - 4u_t) = 0$$

weakly two-dimensional waves in shallow water

- almost periodic solutions in terms of theta functions on arbitrary compact Riemann surfaces (Krichever 1978)

$$u = 2\partial_x^2 \ln \Theta(\mathbf{U}x + \mathbf{V}y + \mathbf{W}t + \mathbf{D}) + 2c$$

- $\mathbf{D} \in \mathbb{R}^g$ arbitrary

- Riemann theta function

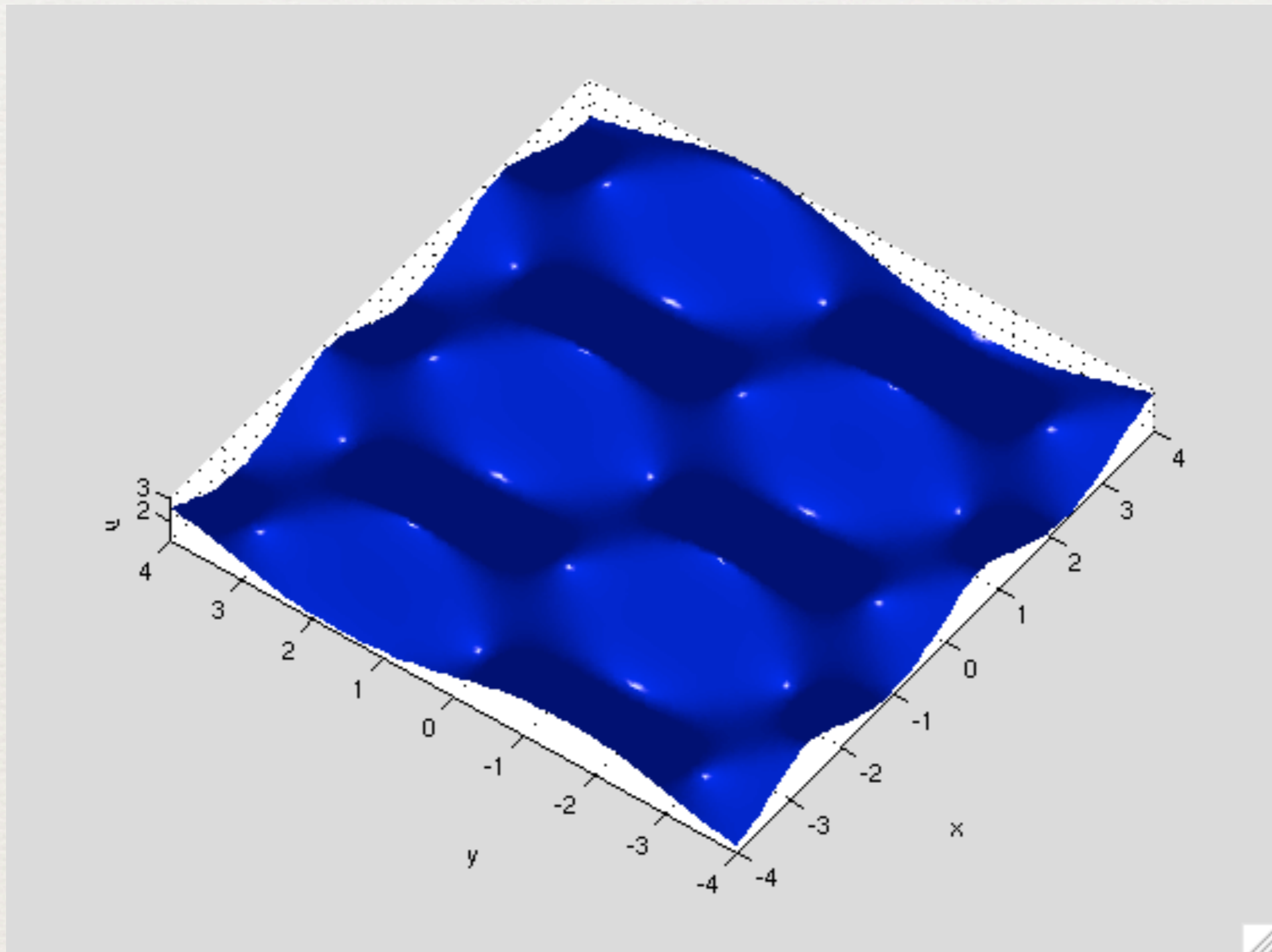
$$\Theta(\mathbf{x}|\mathbf{B}) = \sum_{\mathbf{n} \in \mathbb{Z}^g} \exp \{i\pi \langle \mathbf{B}\mathbf{n}, \mathbf{n} \rangle + 2\pi i \langle \mathbf{n}, \mathbf{x} \rangle\}$$

- \mathbf{B} Riemann matrix, matrix of b -periods of the holomorphic differentials

- $\mathbf{U}, \mathbf{V}, \mathbf{W}$, vectors expressible in terms of derivatives of the holomorphic differentials, c constant expressible in terms of theta functions

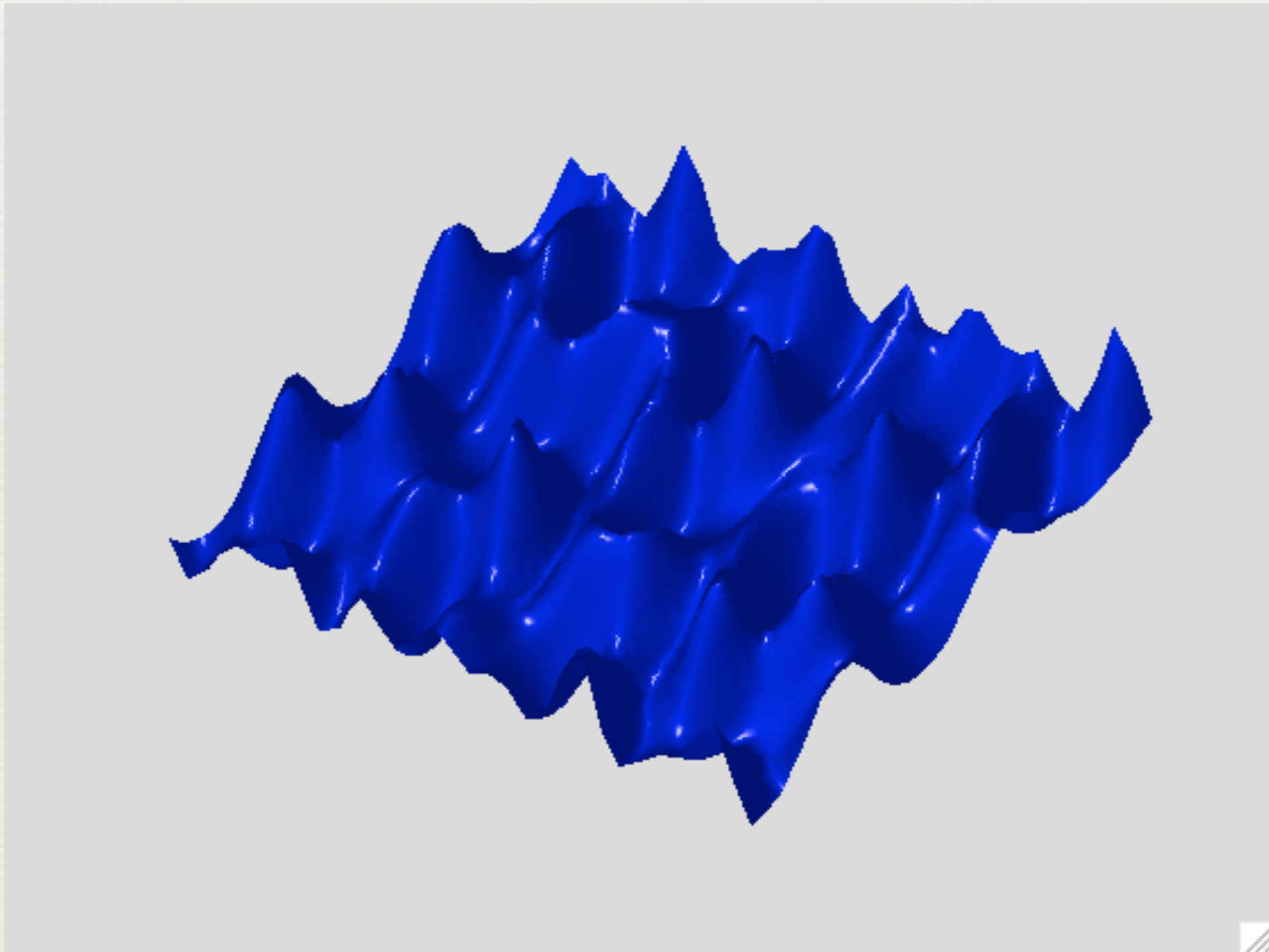
Hyperelliptic solutions ($g=2$)

Hyperelliptic solutions ($g=2$)



Hyperelliptic solution ($g=4$)

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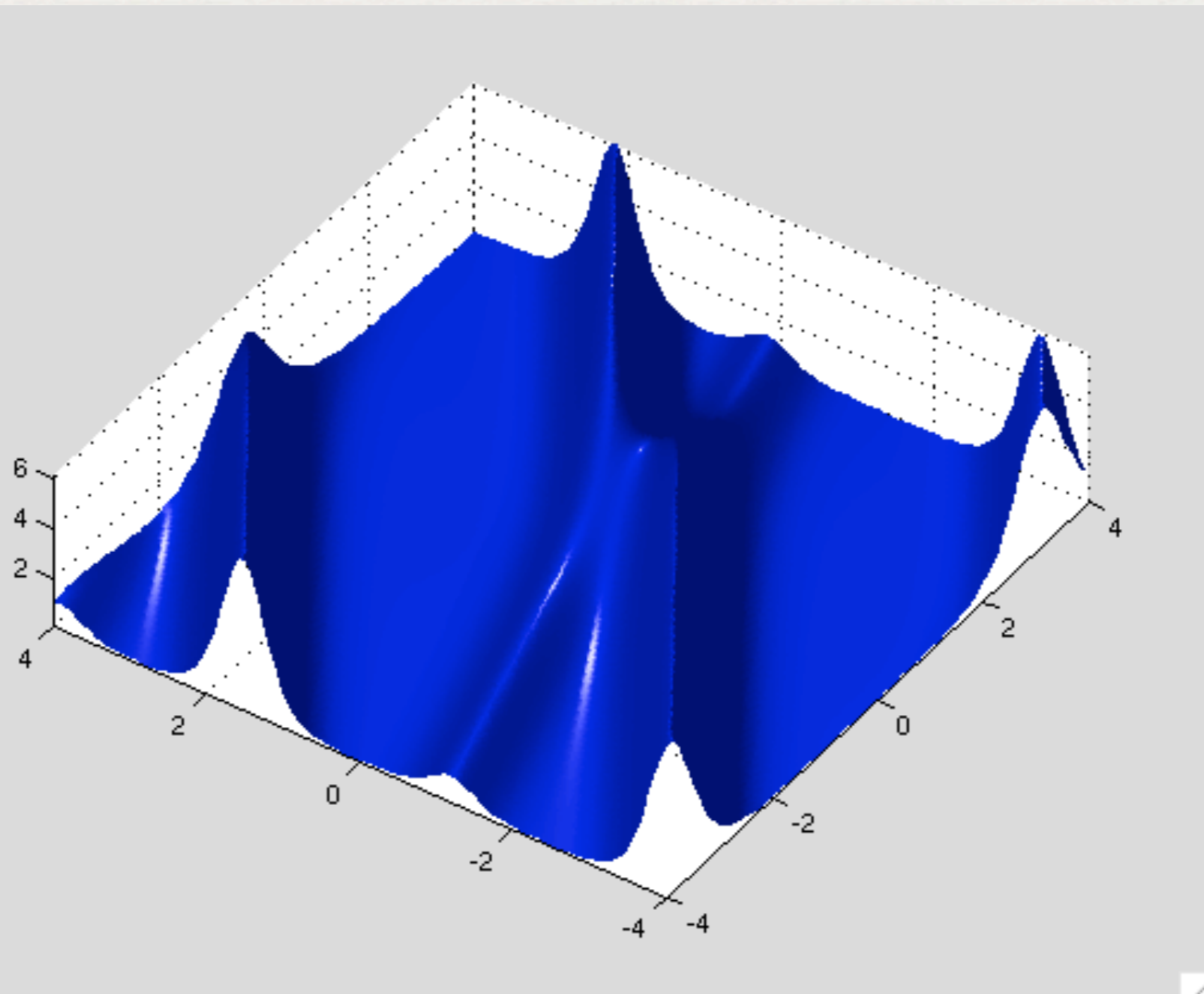


(Line)Solitons (localized in one direction), 2-soliton

- ♦ branch points coincide pairwise, surface of genus 0 in the limit

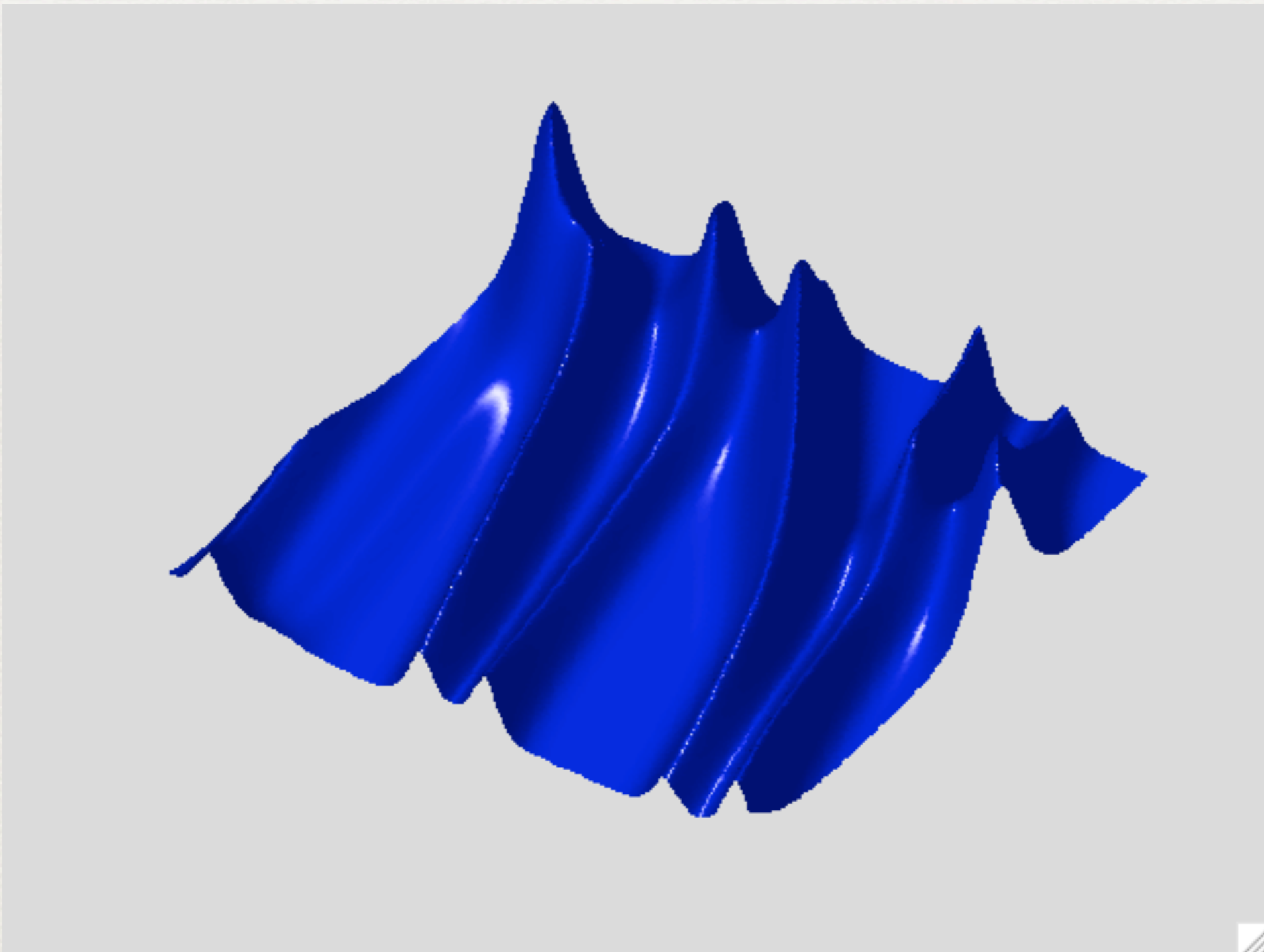
(Line)Solitons (localized in one direction), 2-soliton

- ♦ branch points coincide pairwise, surface of genus 0 in the limit



(Line) Solitons, 4-soliton

(Line) Solitons, 4-soliton



Symbolic vs. numerical

- ♦ Bobenko, Bordag (1989), Schottky uniformizations
- ♦ Deconinck, v. Hoeij, Patterson: *algcurves* package in Maple (2001), symbolic approach, exact expressions (e.g. $\text{RootOf}(x^2-2)$) manipulated and numerically evaluated, in principle infinite precision
- ♦ Frauendiener, K.: fully numeric approach (*floating point*), hyperelliptic curves (1998), much more rapid, allows study of families of curves and of more complicated curves

Ernst equation and Bianchi surfaces

- Bianchi: Gauss-Weingarten equations with spectral parameter
- Ernst equation: Maison, Belinski-Zakharov 1978

$$\Phi_{,\xi} = \frac{\mathcal{J}_{,\xi} \mathcal{J}^{-1}}{1 - \gamma} \Phi, \quad \Phi_{,\bar{\xi}} = \frac{\mathcal{J}_{,\bar{\xi}} \mathcal{J}^{-1}}{1 + \gamma} \Phi$$

where $\xi = \zeta - i\rho$ and

$$\mathcal{J} = \frac{1}{f} \begin{pmatrix} 1 & -b \\ -b & f^2 + b^2 \end{pmatrix}$$

$$\gamma = \frac{2}{\xi - \bar{\xi}} \left(K - \frac{\xi + \bar{\xi}}{2} + \sqrt{(K - \xi)(K - \bar{\xi})} \right)$$

- spectral parameter K on family of Riemann surfaces of genus 0, branch points dependent on physical coordinates (non-autonomous system), Gerch group

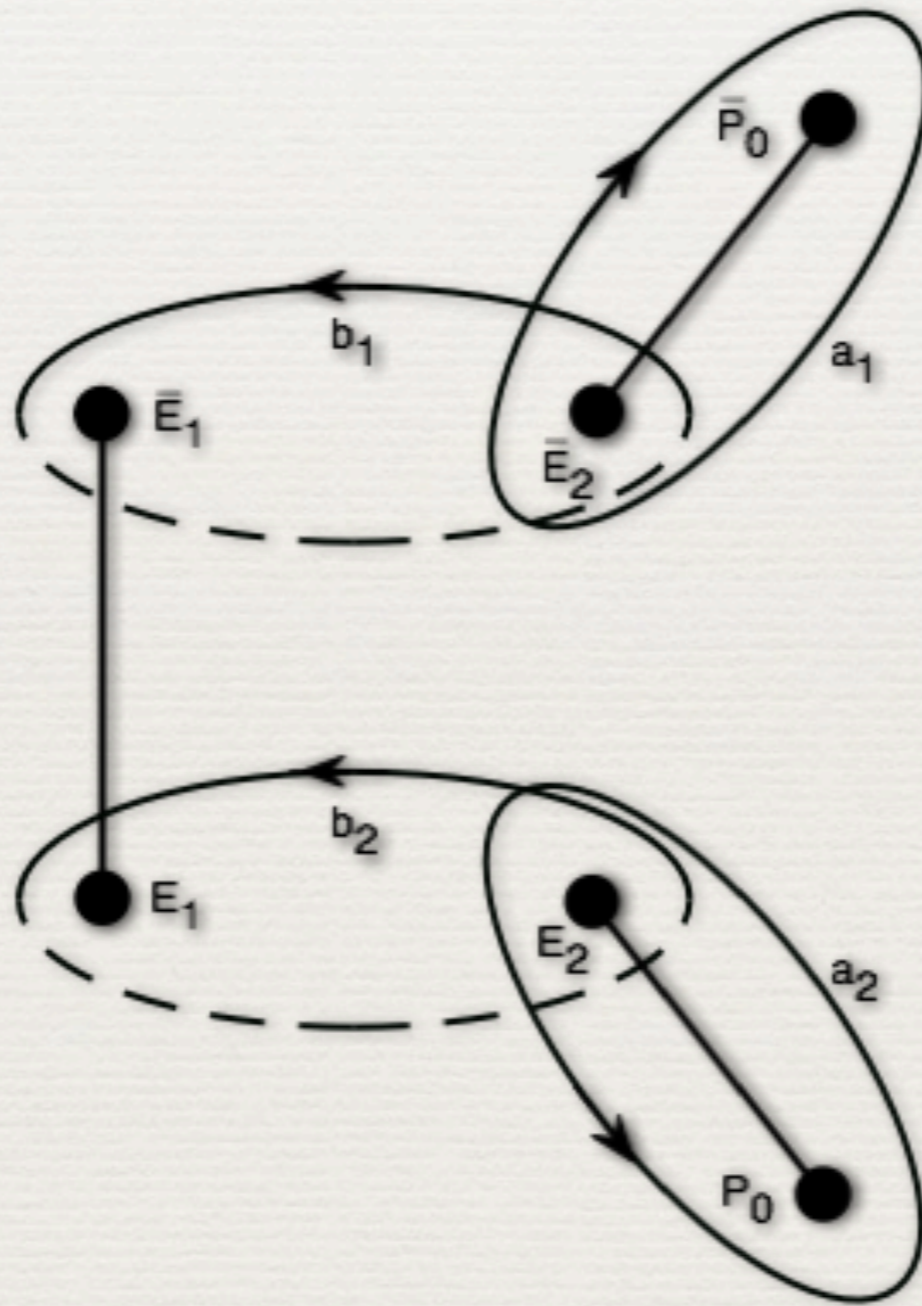
$$\mu^2 = (K - \xi)(K - \bar{\xi})$$

- 2-soliton solution: Kerr black hole

$$\mathcal{E} = \frac{e^{-i\varphi} r_+ + e^{i\varphi} r_- - 2m \cos \varphi}{e^{-i\varphi} r_+ + e^{i\varphi} r_- + 2m \cos \varphi}$$

where $r_{\pm} = \sqrt{(\zeta \pm m \cos \varphi)^2 + \rho^2}$; mass m , angular momentum $J = m^2 \sin \varphi$, horizon on the axis $[-m \cos \varphi, m \cos \varphi]$, $\varphi = 0$: static, spherically symmetric Schwarzschild solution, $\varphi = \pi/2$: extreme Kerr solution (degenerate horizon)

Canonical Cycles ($g=2$)



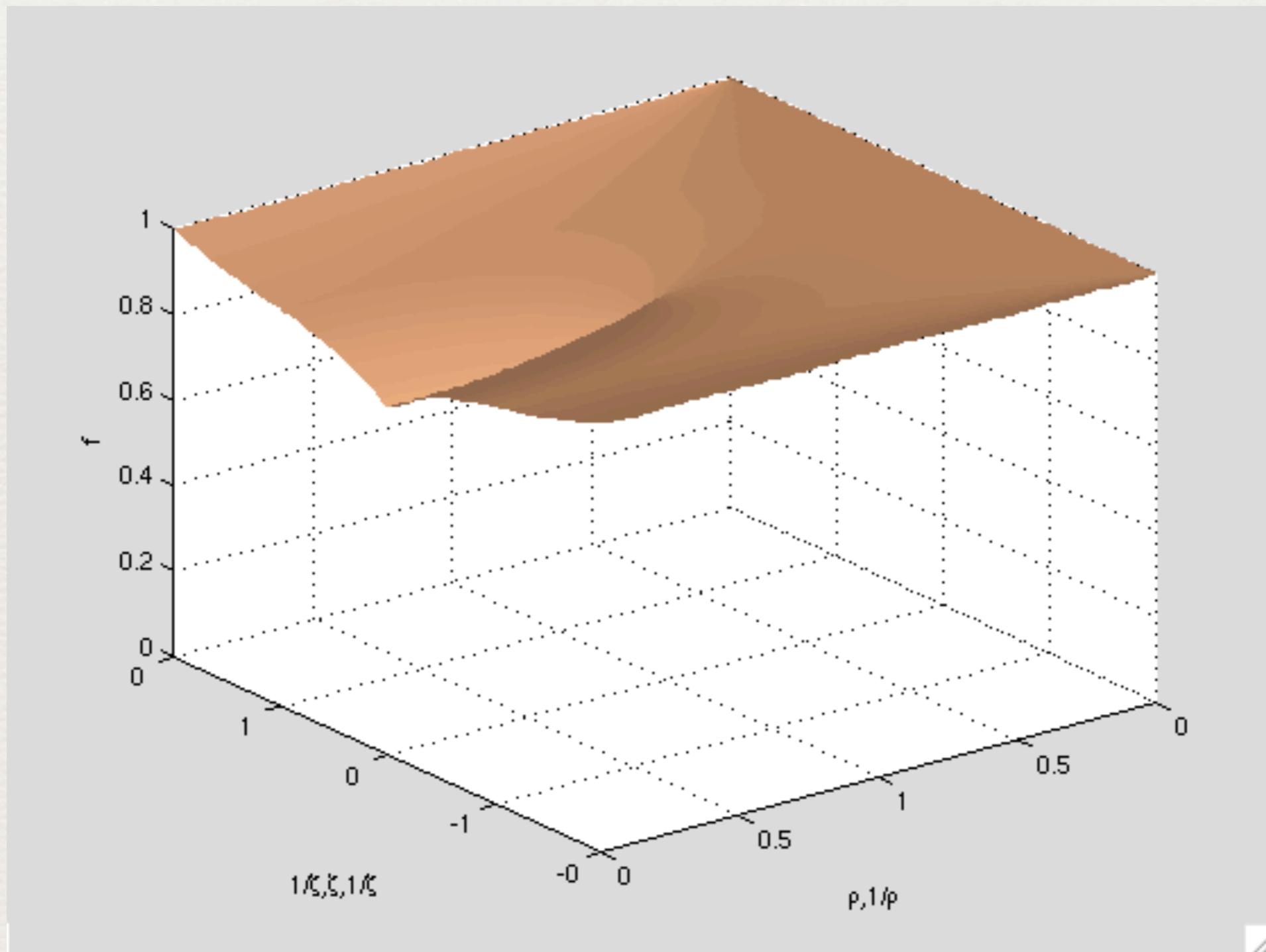
$$P_0 = \zeta - i\rho$$

Ernst potential, Newtonian-ultrarelativistic

Korotkin 1989, K., Richter 1998

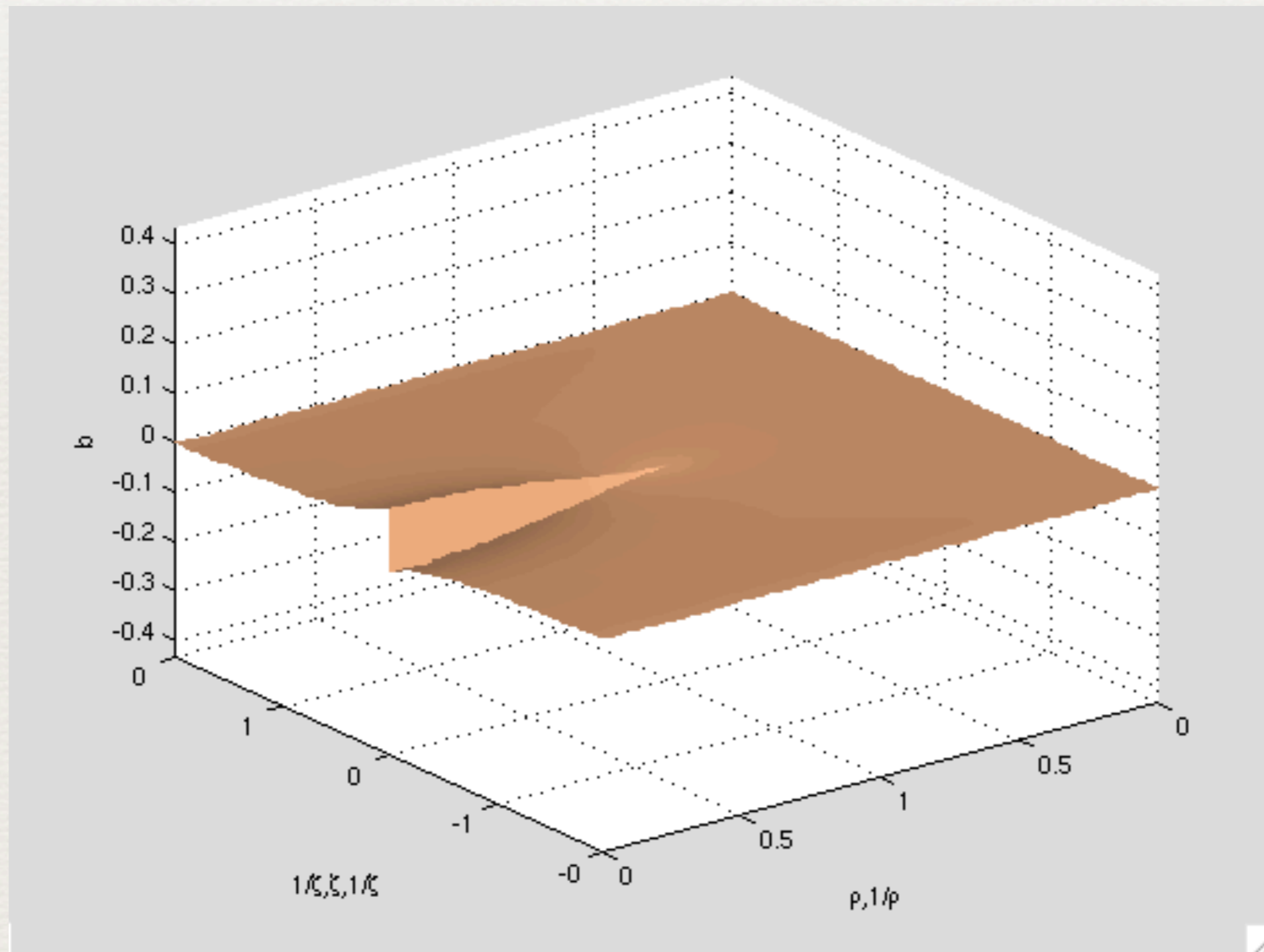
Ernst potential, Newtonian-ultrarelativistic

Korotkin 1989, K., Richter 1998



Ernst potential,
imaginary part

Ernst potential, imaginary part



Outline

- ♦ Riemann surfaces and algebraic curves
- ♦ Branch points and singular points
- ♦ Monodromy and homology
- ♦ Puiseux expansions and holomorphic differentials
- ♦ Real Riemann surfaces
- ♦ Theta functions
- ♦ Performance tests and examples

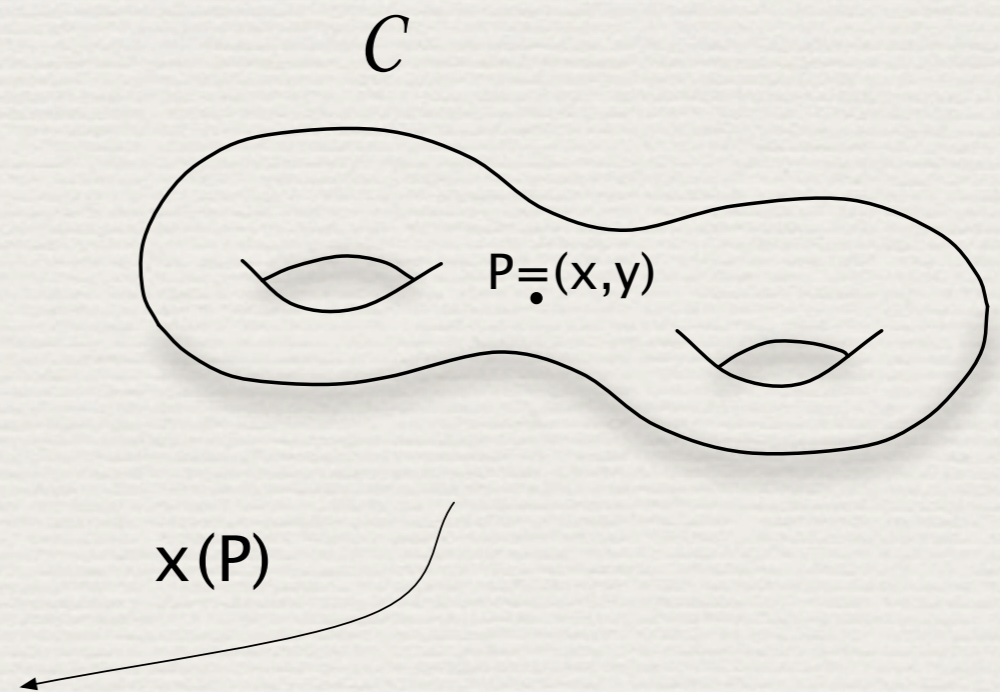
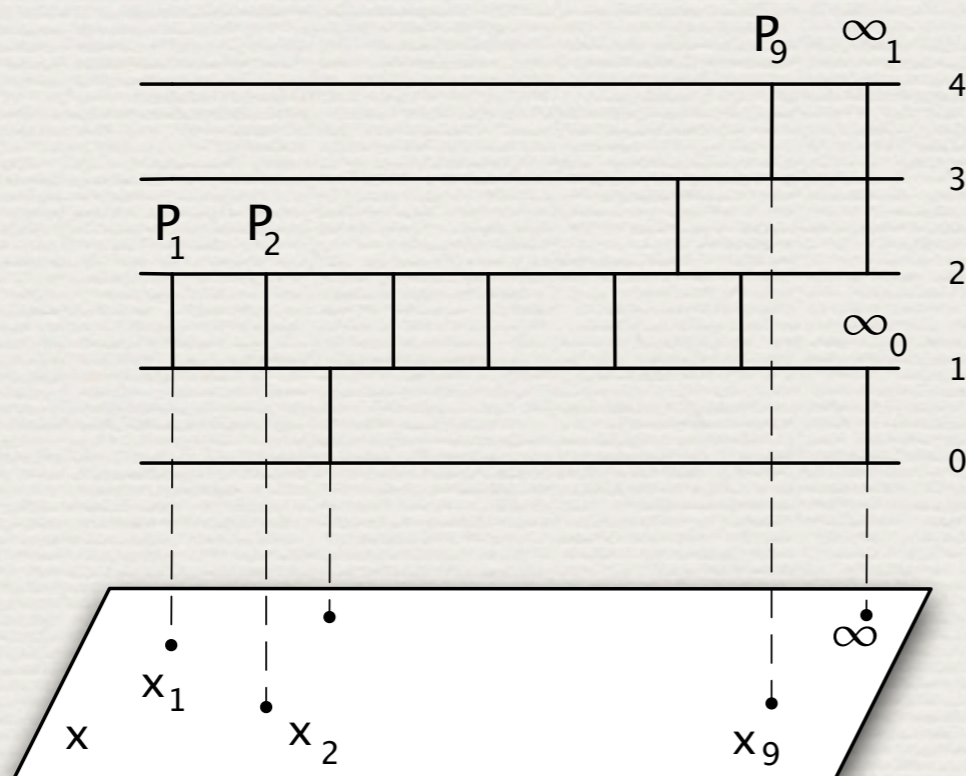
Riemann surfaces

- ♦ Definition: A Riemann surface is a connected one-dimensional complex analytic manifold, i.e., a connected two-dimensional real manifold R with a complex structure Σ on it
- ♦ Theorem: All compact Riemann surfaces can be described as compactifications of non-singular algebraic curves

Algebraic curves

- Definition: plane algebraic curve C subset in \mathbb{C}^2 ,
 $C = \{(x, y) \in \mathbb{C}^2 \mid f(x, y) = 0\}$,

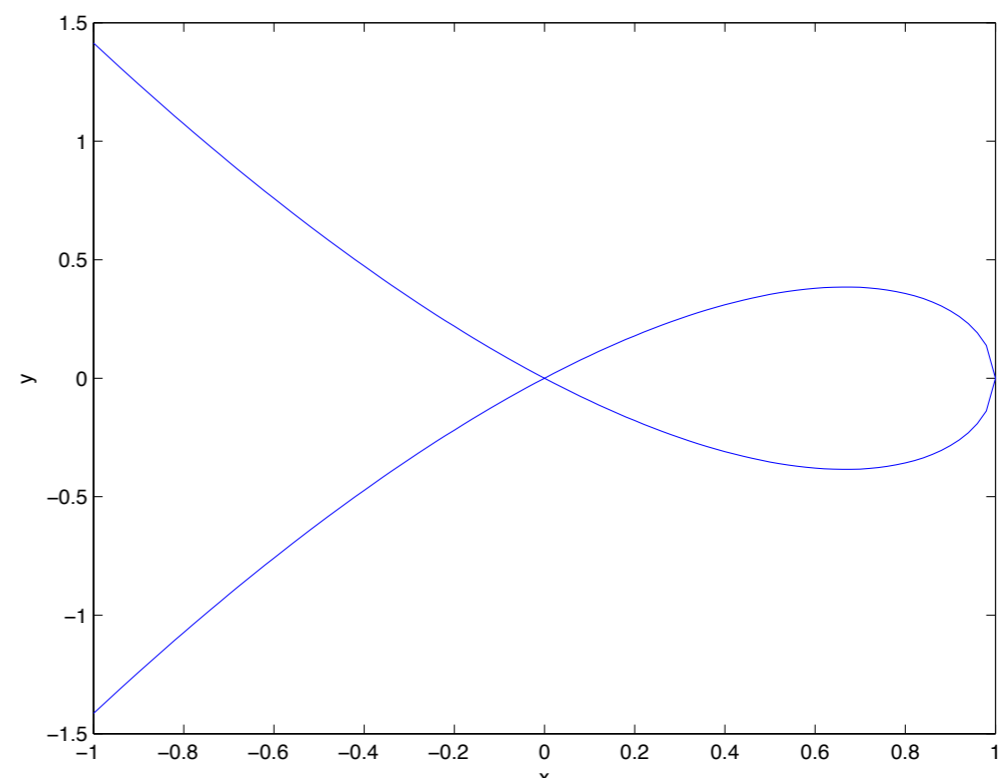
$$f(x, y) = \sum_{i=0}^M \sum_{j=0}^N a_{ij} x^i y^j = \sum_{j=0}^N a_j(x) y^j$$



Critical points

- general position: N distinct solutions y_n for given x , N sheets of the Riemann surface
- Implicit function theorem: unique solution to $f(x, y) = 0$ in vicinity of solution (x_0, y_0) if $f_y(x_0, y_0) \neq 0$
- branch point: $f(x_0, y_0) = f_y(x_0, y_0) = 0$, but $f_x(x_0, y_0) \neq 0$
singular point: $f(x_0, y_0) = f_y(x_0, y_0) = f_x(x_0, y_0) = 0$
- critical points given by the resultant $R(x)$ of $Nf - f_y y$ and f_y

simple double point:
$$y^2 + x^3 - x^2 = 0$$



Resultant

- resultant of $Nf - f_y y$ and f_y , $2N \times 2N$ Sylvester determinant

$$R(x) =$$

$$\begin{pmatrix} a_{N-1} & 2a_{N-2} & \dots & Na_0 & 0 & \dots & \dots & 0 \\ 0 & a_{N-1} & 2a_{N-2} & \dots & Na_0 & 0 & \dots & 0 \\ \vdots & \ddots & & & & & \ddots & \vdots \\ 0 & \dots & \dots & 0 & a_{N-1} & 2a_{N-2} & \dots & Na_0 \\ Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 & 0 & \dots & \dots & 0 \\ 0 & Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 & 0 & \dots & 0 \\ \vdots & \ddots & & & & & \ddots & \vdots \\ 0 & \dots & \dots & 0 & Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 \end{pmatrix}$$

Numerical root finding

- construct companion matrix (has $R(x)$ as the characteristic polynomial), find eigenvalues with machine precision
- multiple zeros are not found with machine precision, ex. $y^7 = x(x-1)^2$ Klein curve, $R(x) = x^6(x-1)^{12}$, `roots(R(x))` returns the following cluster of roots

```
1.1053 + 0.0297i
1.1053 - 0.0297i
1.0736 + 0.0790i
1.0736 - 0.0790i
1.0224 + 0.1032i
1.0224 - 0.1032i
0.9686 + 0.0980i
0.9686 - 0.0980i
0.9264 + 0.0686i
0.9264 - 0.0686i
0.9037 + 0.0245i
0.9037 - 0.0245i,
```

polynomial root finding

- ♦ badly conditioned problem
- ♦ Zeng: *multroot package* for multiple roots
(Newton iteration, minimize error by choice of multiplicity structure)
- ♦ resultant high order polynomial, therefore direct Newton iteration in x and y . Initial iterates from resultant with respect to x and y , pairing
- ♦ postprocessing for higher order zeros

Singularities

- multiple roots are tested for vanishing $f_x(x, y)$
- infinity: homogeneous coordinates X, Y, Z
via $x = X/Z, y = Y/Z$

$$F(X, Y, Z) = Z^d f(X/Z, Y/Z) = 0$$

infinite points: $Z = 0$, finite points: $Z = 1$

- Singular points at infinity:
 $F_X(X, Y, 0) = F_Y(X, Y, 0) = F_Z(X, Y, 0) = 0$

Example

- curve

$$f(x, y) = y^3 + 2x^3y - x^7 = 0,$$

- finite branch points

bpoints =

-0.3197 - 0.9839i

0.8370 - 0.6081i

-1.0346

0

0.8370 + 0.6081i

-0.3197 + 0.9839i

- singularities,

sing =	X	Y	Z	
	0	0	1	4
	0	1	0	9

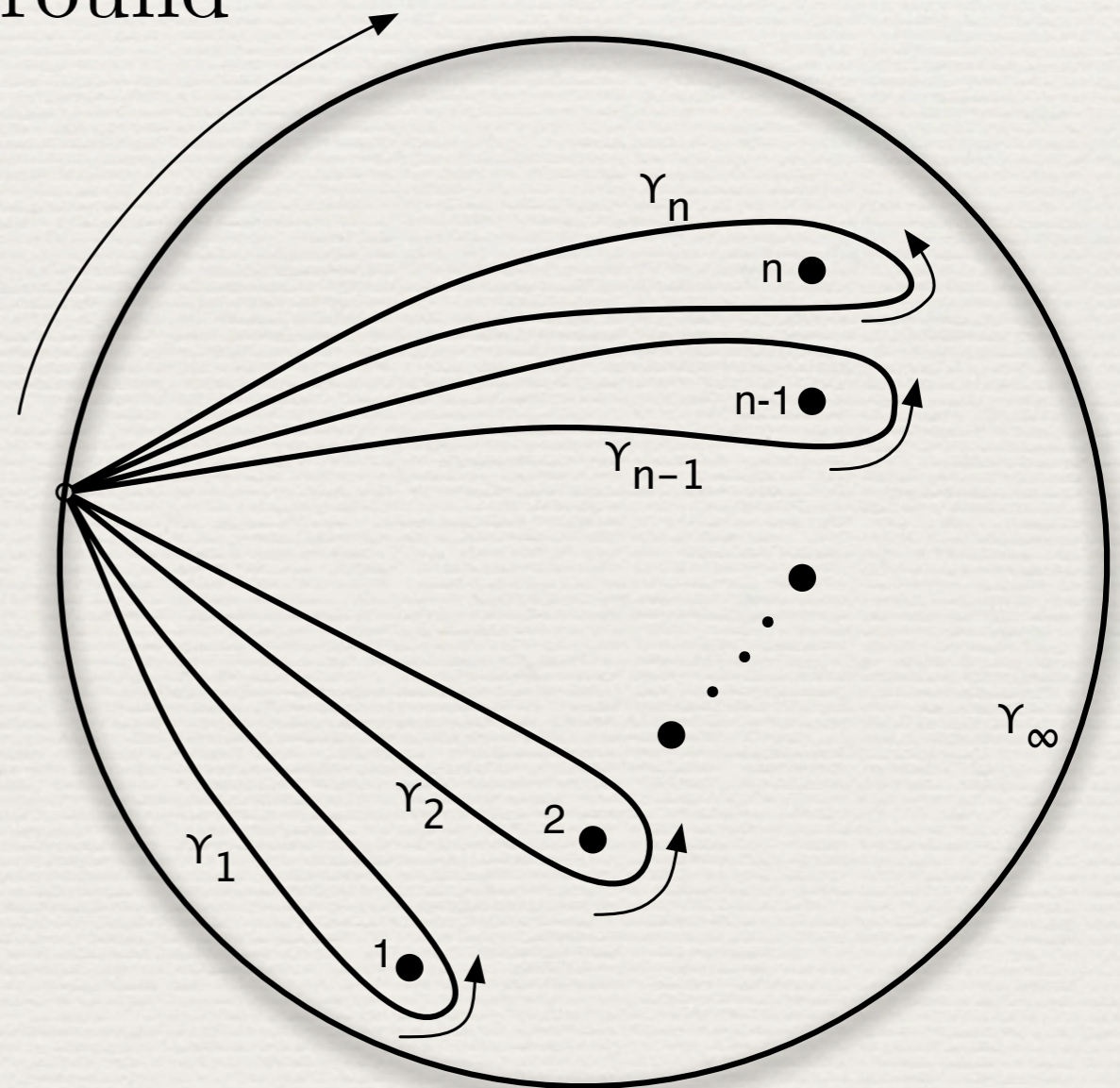
corresponding to $x = y = 0$ and $Y = 1, X = Z = 0$

Fundamental group

- branching structure at critical points, lift closed contours in the base around points b_1, \dots, b_n to the covering

- generators $\{\gamma_k\}_{k=1}^n$ of fundamental group $\pi_1(\mathbb{C}\mathbb{P}^1 \setminus \{b_1, \dots, b_n\})$

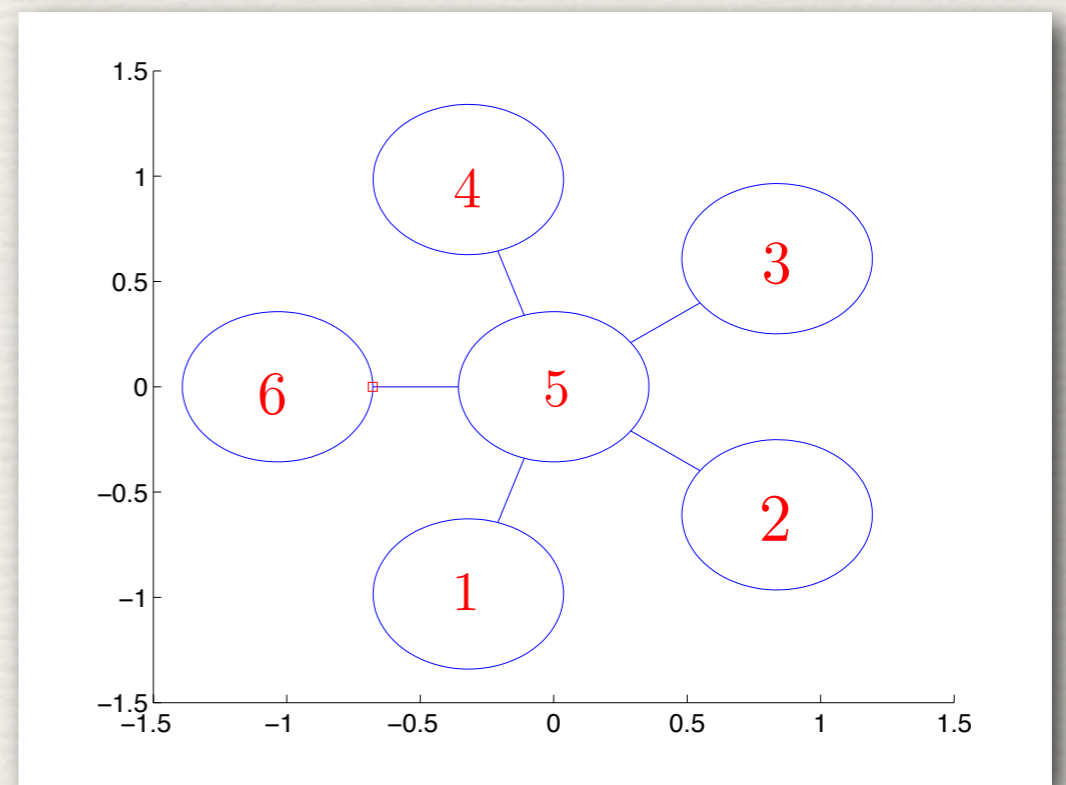
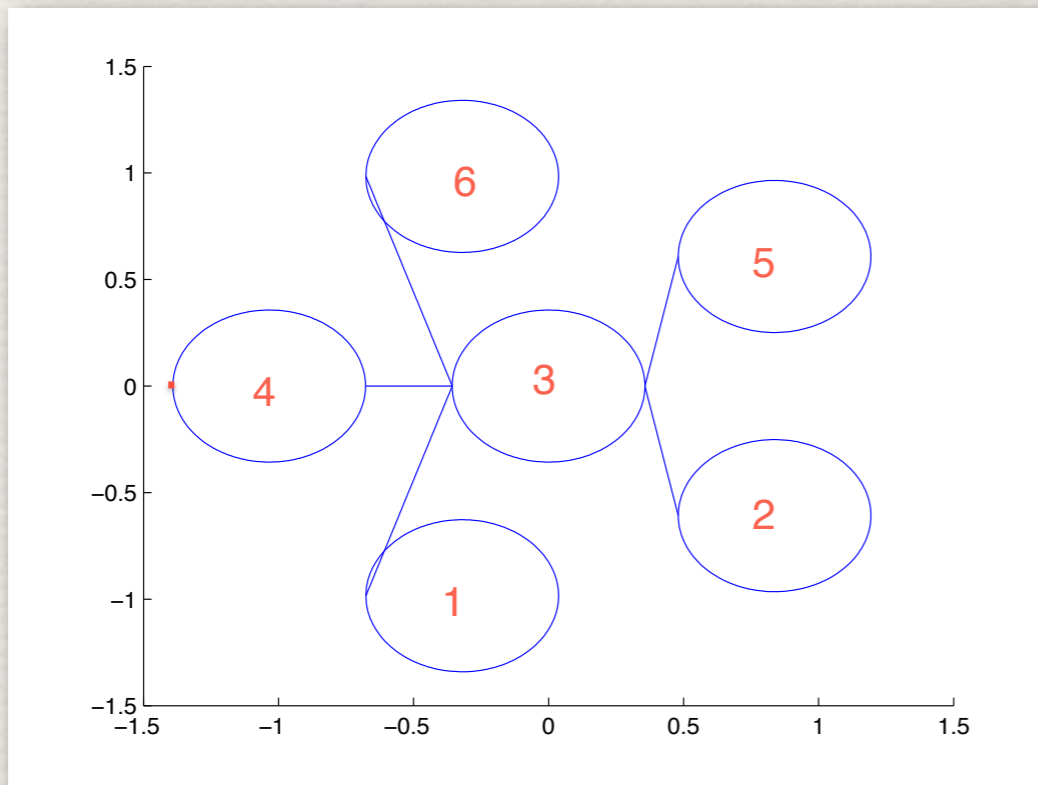
$$\gamma_1 \gamma_2 \cdots \gamma_n \gamma_\infty = \text{id}$$



Minimal spanning tree

- ◆ Maple: halfcircles around critical points, deformation of connecting paths
- ◆ shortest integration paths: start with critical point close to the base, choose point with minimal distance, iterate (Frauendiener, K, Shramchenko 2011)

◆ ex:



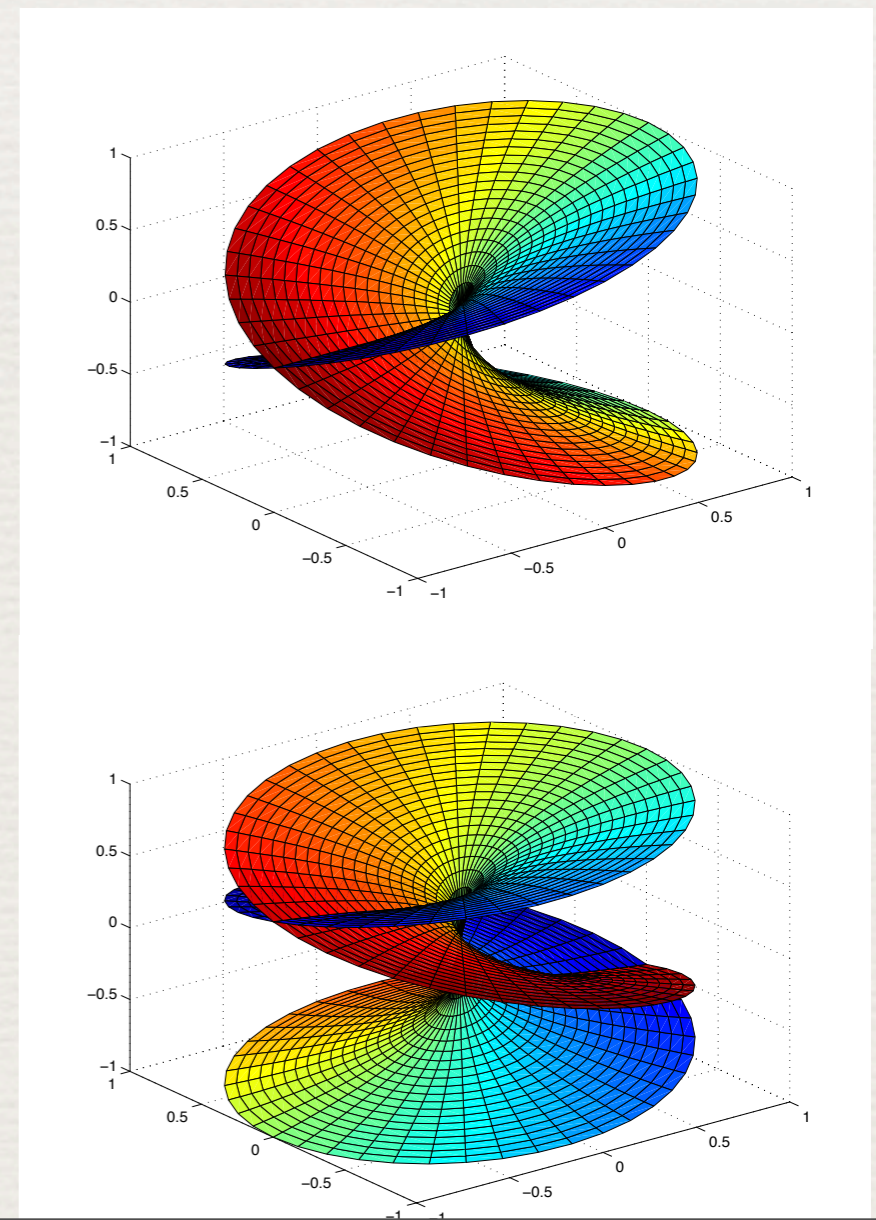
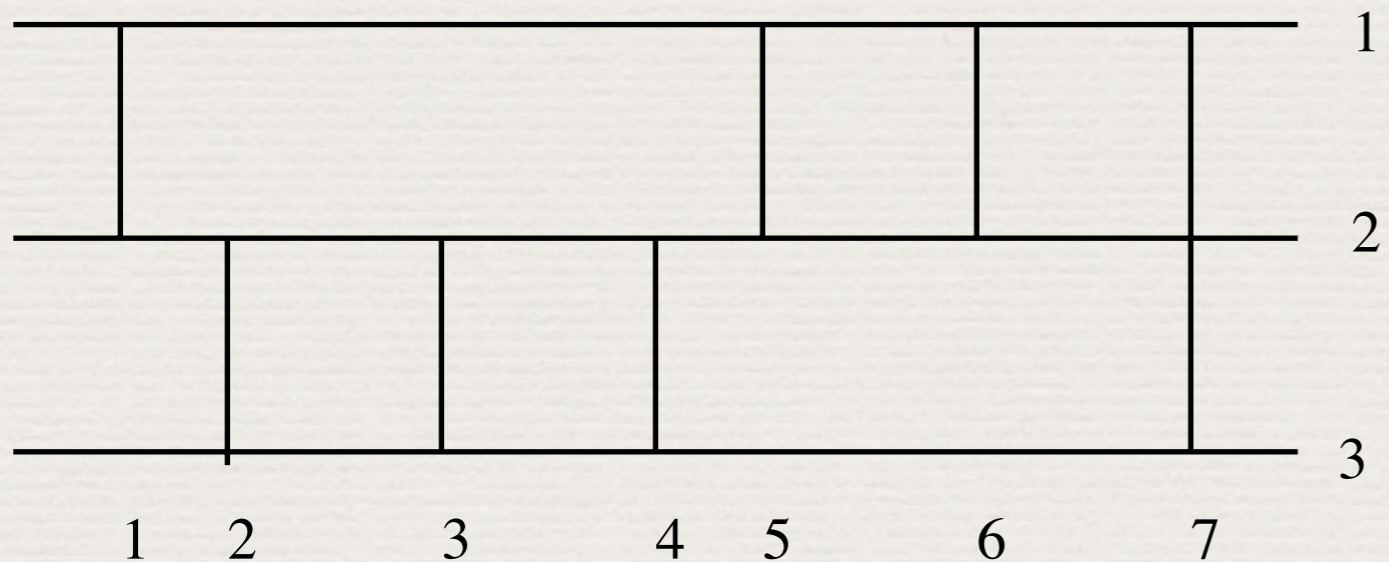
Monodromies

- ♦ analytic continuation along a generator: sheets can change
- ♦ monodromy at infinity follows from condition on generators

• ex.:

Mon =

2	1	1	1	2	2	2
1	3	3	3	1	1	3
3	2	2	2	3	3	1

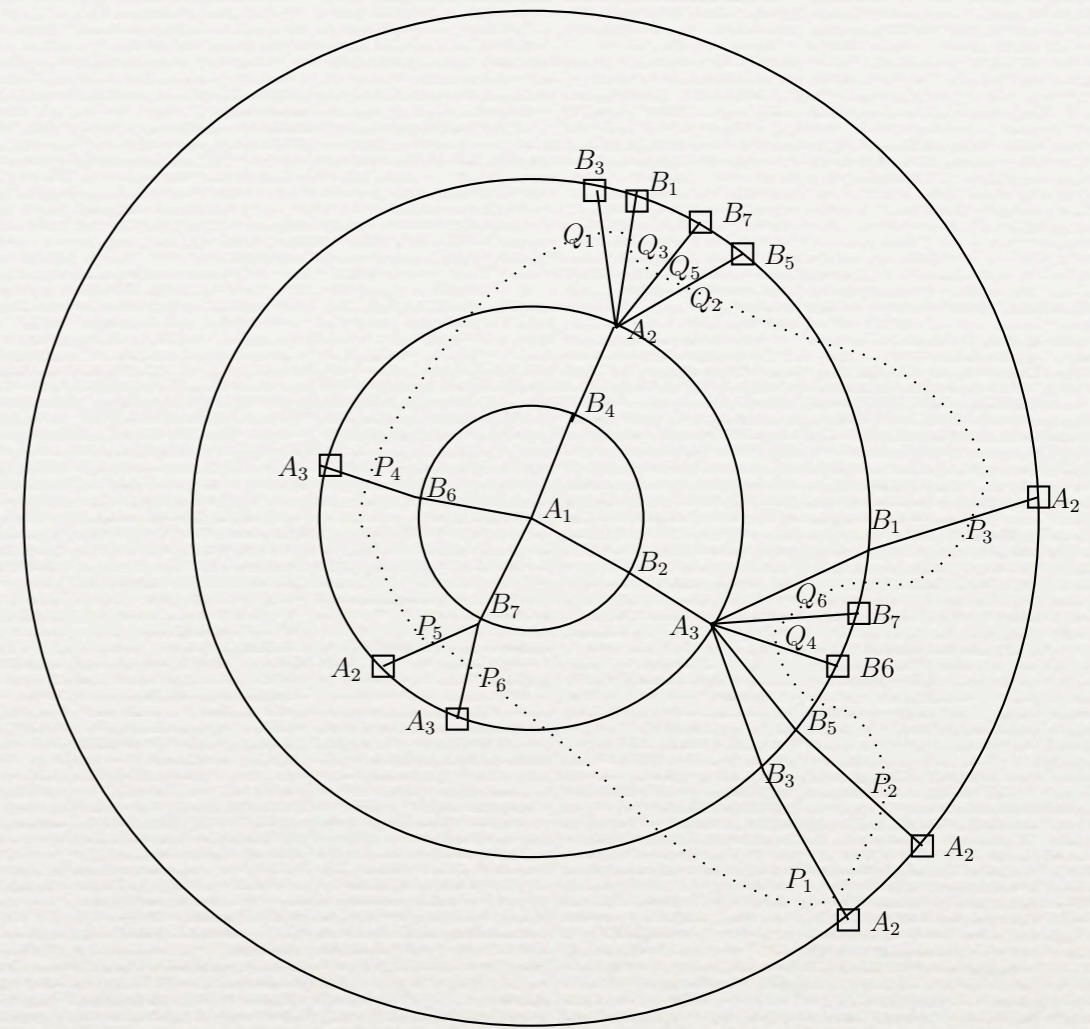


Homology

• ex.:

Mon =

1	3	1	2	1	3	2
3	2	3	1	3	2	3
2	1	2	3	2	1	1.



- ♦ Tretkoff-Tretkoff algorithm: Riemann surface connected, planar tree for given monodromies
- ♦ $2g+N-1$ closed contours built from the generators of the fundamental group, with known intersection numbers
- ♦ canonical basis of the homology:

$$a_i \circ b_j = -b_j \circ a_i = \delta_{ij} \quad i, j = 1, \dots, g$$

Canonical cycles

- canonical basis of the homology :

$$a_i = \sum_{j=1}^{2g+N-1} \alpha_{ij} c_j, \quad b_i = \sum_{j=1}^{2g+N-1} \alpha_{i+g,j} c_j, \quad i = 1, \dots, g$$

c_j : $2g + N - 1$ closed contours from the planar graph

- remaining cycles homologous to zero (test for numerical accuracy)

$$0 = \sum_{j=1}^{2g+N-1} \alpha_{ij} c_j, \quad i = 2g + 1, \dots, 2g + N - 1$$

- ex.:

acycle{1} =

1 4 2 3 3 2 1

acycle{2} =

1 4 2 1 3 2 1

bcycle{1} =

1 6 3 2 1

bcycle{2} =

2 3 3 2 3 5 2,

Puiseux expansion

- desingularization: atlas of local coordinates to identify all sheets in the vicinity of the singularity
- $y^2 = x$, no Taylor expansion $y(x)$ near $(0, 0)$, Puiseux expansion

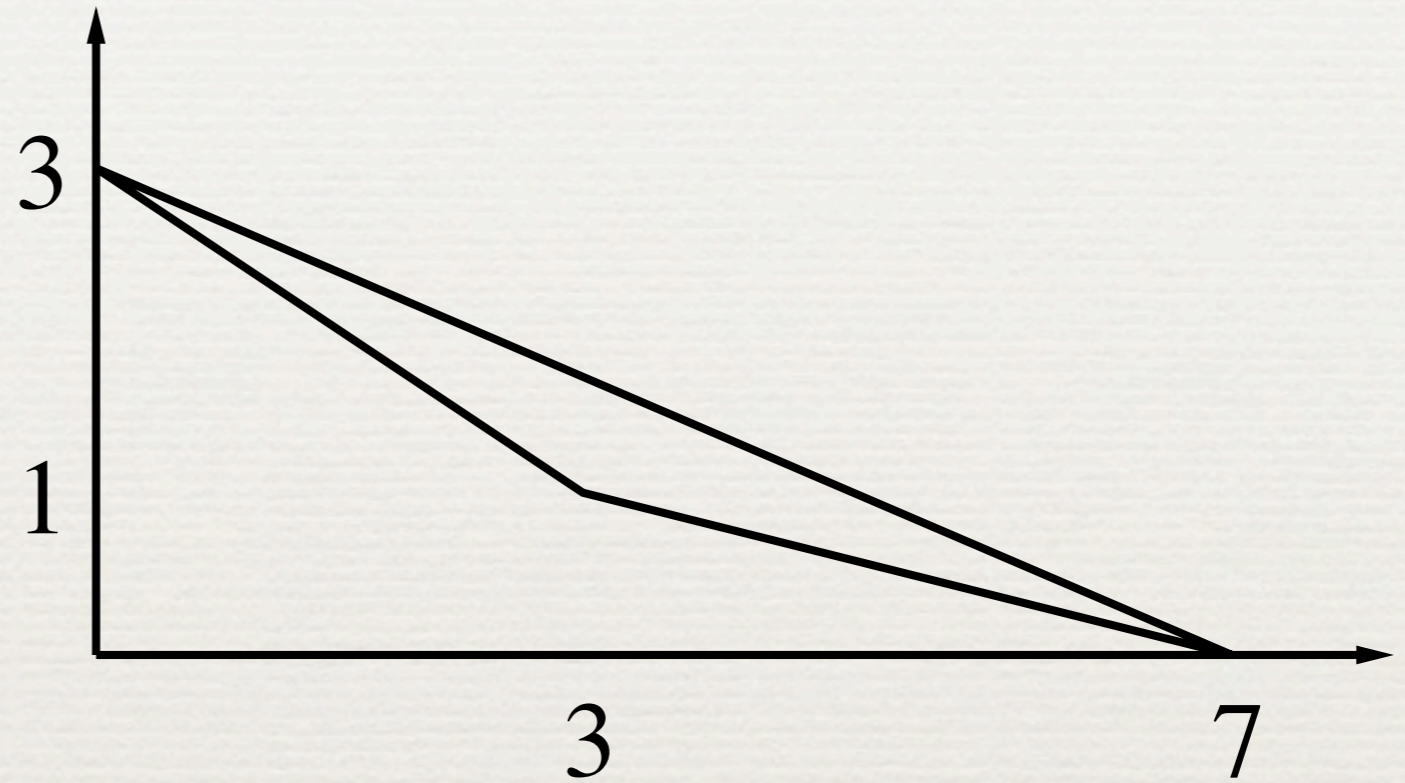
$$x = t^r, \quad y = \alpha_1 t^{s_1} + \dots$$

$$r, s_1, \dots \in \mathbb{N}, \quad \alpha_i \in \mathbb{C} \text{ for } i = 1, 2, \dots$$

- $y = 0$ zero of order m for $f(0, y) = 0$, m inequivalent expansions needed to identify all sheets, *singular part*

Newton polygon

- ex.: $f(x, y) = y^3 + 2x^3y - x^7 = 0$



PuiExp{1} =

2.0000	3.0000	$0 + 1.4142i$
2.0000	3.0000	$0 - 1.4142i$
1.0000	4.0000	0.5000

PuiExp{2} =

4.0000	7.0000	-1.0000
4.0000	7.0000	$0 + 1.0000i$
4.0000	7.0000	$0 - 1.0000i$
4.0000	7.0000	1.0000

PuiExp{1} for $(0, 0)$ $([0, 0, 1])$, PuiExp{2} for infinity $([0, 1, 0])$

Holomorphic 1-forms

- holomorphic in each coordinate chart, g -dimensional space
- Noether:

$$\omega_k = \frac{P_k(x, y)}{f_y(x, y)} dx ,$$

adjoint polynomials $P_k(x, y) = \sum_{i+j \leq d-3} c_{ij}^{(k)} x^i y^j$,
degree at most $d - 3$ in x and y ($d = \max(i + j)$ for $a_{ij} \neq 0$)

- singular point P : δ_P conditions via Puiseux expansions
- infinity: homogeneous coordinates
- ex.: $f(x, y) = y^3 + 2x^3y - x^7 = 0$

$$\omega_1 = \frac{x^3}{3y^2 + 2x^3}, \quad \omega_2 = \frac{xy}{3y^2 + 2x^3}$$

Cauchy integral approach

- numerical problem: cancellation errors, ex. $\frac{e^x - 1}{x}$ for $x \rightarrow 0$
- Cauchy formula

$$f(t) = \frac{1}{2\pi i} \int_{\gamma} \frac{f(t')}{t' - t} dt'$$

- closed contours around critical points identified via monodromy group
- series in t for holomorphic f ($|t| < |t'|$)

$$f(t) = \frac{1}{2\pi i} \sum_{n=0}^{\infty} t^n \int_{\gamma} f(t') \frac{dt'}{(t')^{n+1}}$$

- Puiseux series: $f = y$;
holomorphicity condition for differentials (no negative powers)
- infinity: express γ_{∞} in terms of the γ_i

- infinity: homogeneous coordinates
- singular part of more than one term, additional conditions
- ex.: $f(x, y) = x^3 + 2x^3y - x^7 = 0$

$$c\{1\} =$$

$$\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

$$c\{2\} =$$

$$\begin{array}{ccccc} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

polynomials $P_1 = x^3$ and $P_2 = xy$

Numerical integration

- Gauss-Legendre integration: expansion of integrand in terms of Legendre polynomials $\mathcal{F}(x_l) = \sum_{k=0}^{N_l} a_k \mathcal{P}_k(x_l)$, $l = 0, \dots, N_l$

$$\int_{-1}^1 \mathcal{F}(x) dx \sim \sum_{k=0}^{N_l} a_k \int_{-1}^1 \mathcal{P}_k(x) dx$$

- integration:

$$\int_{-1}^1 \mathcal{F}(x) dx \sim \sum_{k=0}^{N_l} \mathcal{F}(x_k) \mathcal{L}_k$$

- analytic continuation of y_j along the γ_i on the collocation points x_l , integration of the holomorphic differentials

Riemann matrix

- a - and b -periods

$$\mathbf{B} = \mathcal{A}^{-1}\mathcal{B}$$

- numerical asymmetry of Riemann matrix as test
- ex.:

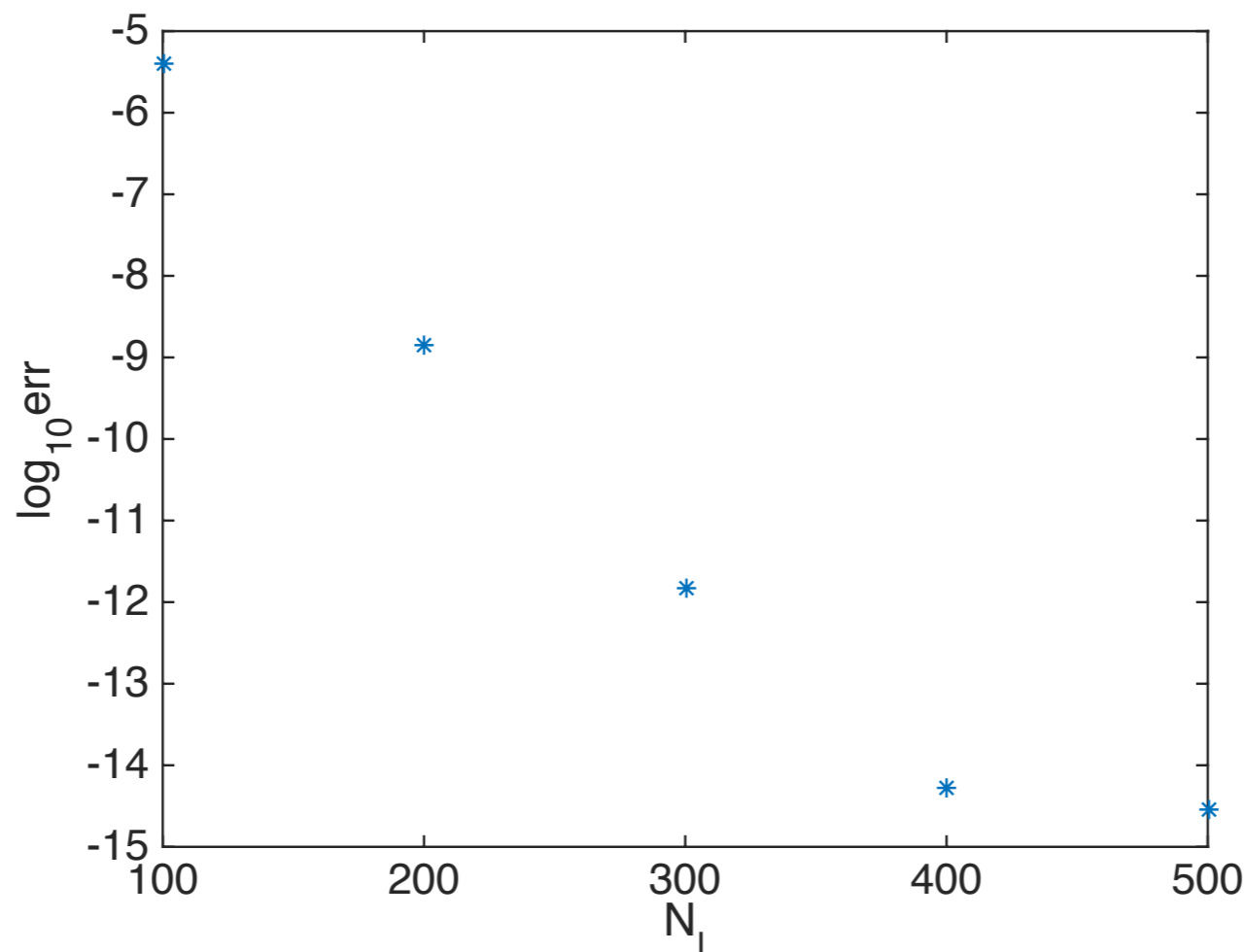
RieMat =

$$\begin{array}{cc} 0.3090 + 0.9511i & 0.5000 - 0.3633i \\ 0.5000 - 0.3633i & -0.3090 + 0.9511i. \end{array}$$

Performance

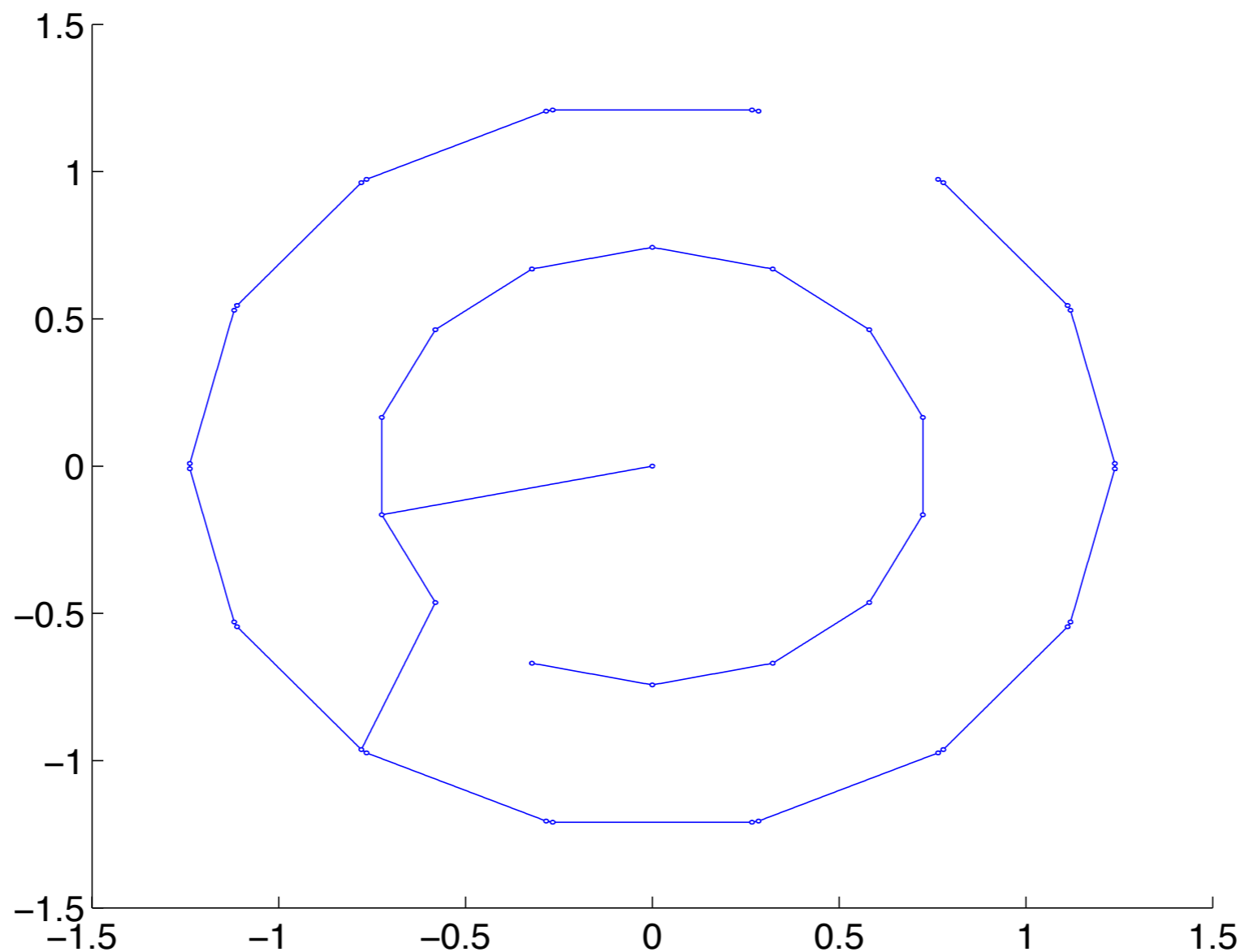
- error: asymmetry of the Riemann matrix and periods of cycles homologous to 0 for

$$f(x, y) = y^9 + 2x^2y^6 + 2x^4y^3 + x^6 + y^2 = 0$$



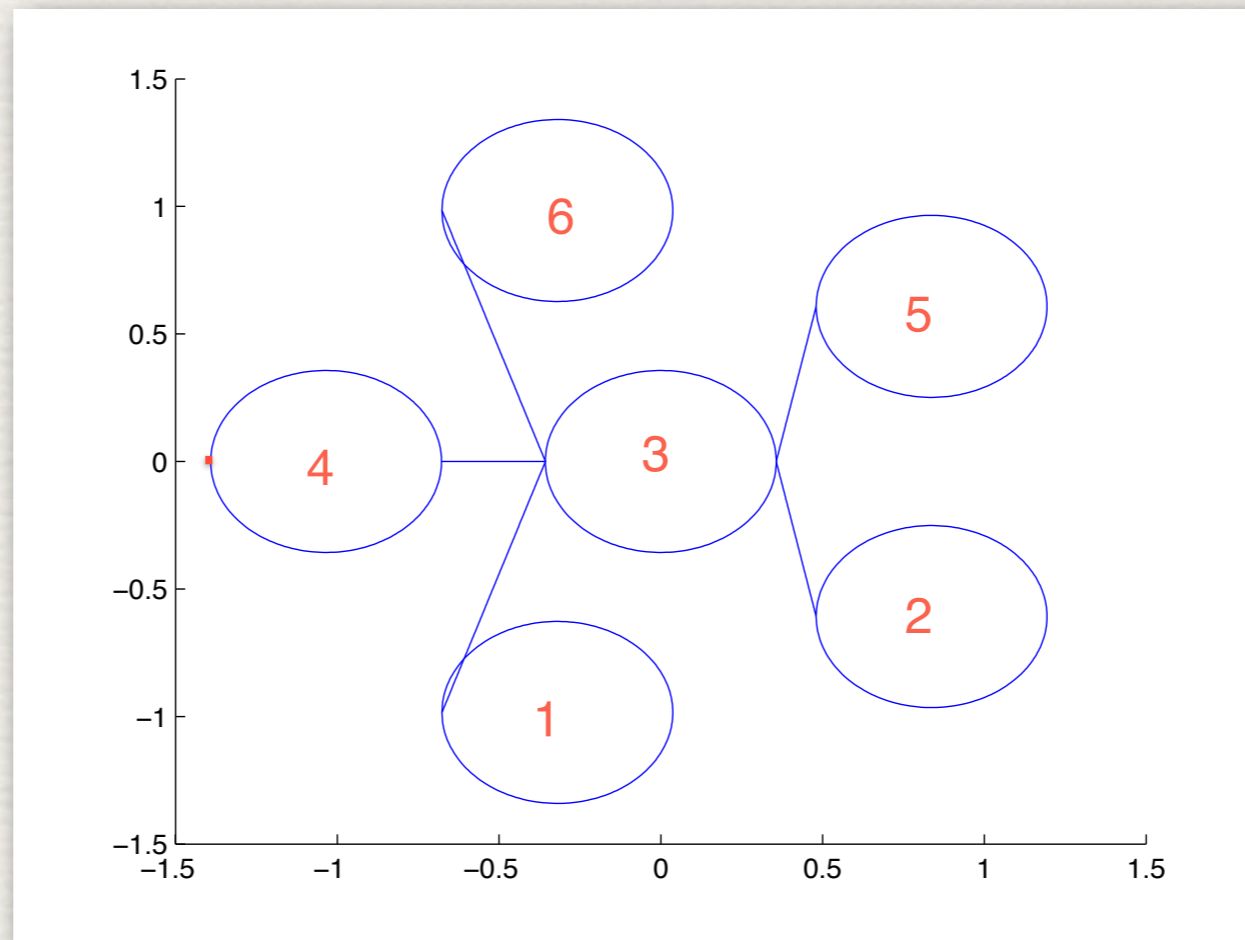
- $$f(x, y) = y^9 + 2x^2y^6 + 2x^4y^3 + x^6 + y^2 = 0$$

genus 16, 42 finite branch points, two singular points $(0, 0, 1)$ and $(1, 0, 0)$,
minimal distance between branch points 0.018



Abel map

- ♦ $A(P)$: determine closest marked point to P , analytic continuation of y from there and integration as before.
- ♦ critical points, infinity: Cauchy formula



Real Riemann surfaces

- ♦ in applications, solutions to PDEs in terms of theta functions must satisfy reality and smoothness conditions
- ♦ real Riemann surfaces: anti-holomorphic involution, convenient form of the homology basis
- ♦ smoothness: study of the theta divisor (zeros of the theta function) (Dubrovin, Natanzon, Vinnikov)

Theta functions

- theta series

$$\Theta_{pq}(z, \mathbb{B}) = \sum_{N \in \mathbb{Z}^g} \exp \{ i\pi \langle \mathbb{B} (N + p), N + p \rangle + 2\pi i \langle z + q, N + p \rangle \}$$

- Deconinck, B., Heil, M., Bobenko, A., van Hoeij, M., Schmies, M.: Computing Riemann theta functions. *Mathematics of Computation*, **73**, 1417–1442 (2004)
- approximated as a sum $|N_i| \leq \mathcal{N}_\epsilon, i = 1, \dots, g$

$$\mathcal{N}_\epsilon > \sqrt{-\frac{\ln \epsilon}{\pi y_{min}}} + \frac{1}{2}$$

Symplectic transformation

-

$$\mathcal{A}_g = \begin{pmatrix} A & B \\ C & D \end{pmatrix}, \quad (1)$$

A, B, C, D $g \times g$ integer matrices

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix}^T \begin{pmatrix} 0_g & I_g \\ -I_g & 0_g \end{pmatrix} \begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} 0_g & I_g \\ -I_g & 0_g \end{pmatrix}; \quad (2)$$

- Riemann matrix

$$\mathbb{H}^g \mapsto \mathbb{H}^g : \quad \mathbb{B} \mapsto \tilde{\mathbb{B}} = (A\mathbb{B} + B)(C\mathbb{B} + D)^{-1}. \quad (3)$$

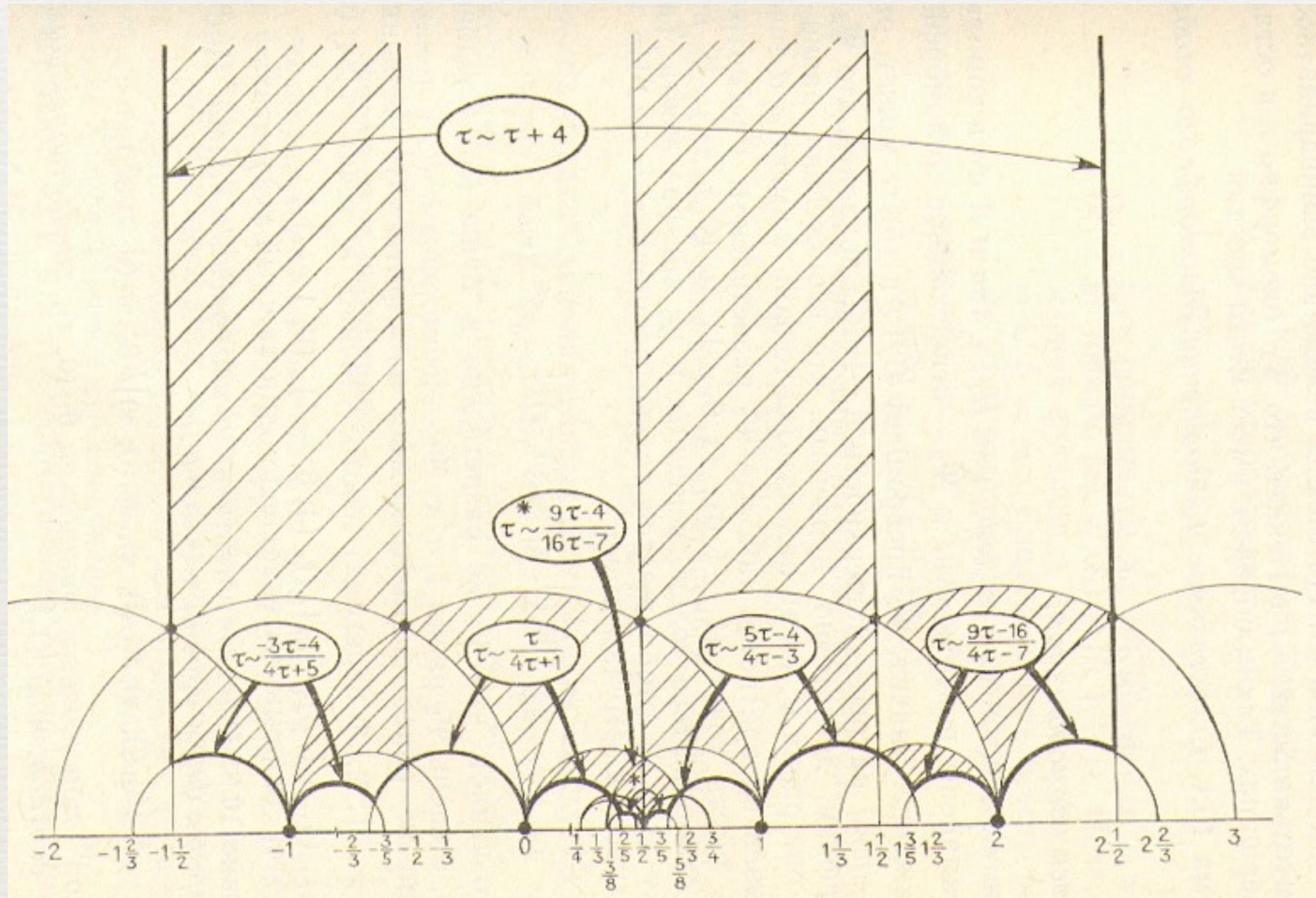
- theta function

$$\Theta_{\tilde{p}\tilde{q}}(\mathcal{M}^{-1}z, \tilde{\mathbb{B}}) = k\sqrt{\det(\mathcal{M})} \exp\left(\frac{1}{2} \sum_{i \leq j} z_i z_j \frac{\partial}{\partial \mathbb{B}_{ij}} \ln \det \mathcal{M}\right) \Theta_{pq}(z), \quad (4)$$

$$\mathcal{M} = C\mathbb{B} + D, \quad \begin{pmatrix} \tilde{p} \\ \tilde{q} \end{pmatrix} = \begin{pmatrix} D & -C \\ -B & A \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix} + \frac{1}{2} \begin{pmatrix} \text{diag}(CD^T) \\ \text{diag}(AB^T) \end{pmatrix}, \quad (5)$$

Fundamental domain

$$|\Re\sigma| \leq \frac{1}{2}, \Im\sigma > \frac{1}{2}\sqrt{3}$$



Mumford: Tata Lectures on Theta Functions

Siegel's fundamental domain

- subset of \mathbb{H}^g such that $\mathbb{B} = X + iY \in \mathbb{H}^g$ satisfies:
 1. $|X_{nm}| \leq 1/2$, $n, m = 1, \dots, g$,
 2. Y is in the fundamental region of Minkowski reductions,
 3. $|\det(C\mathbb{B} + D)| \geq 1$ for all C, D .
- *quasi-inversion*: $\mathbb{B} \mapsto -\mathbb{B}/\mathbb{B}_{11}$

$$\begin{aligned} A &= \begin{pmatrix} 0 & \mathbf{0}_{g-1}^T \\ \mathbf{0}_{g-1} & \mathbf{1}_{g-1, g-1} \end{pmatrix}, & B &= \begin{pmatrix} -1 & \mathbf{0}_{g-1}^T \\ \mathbf{0}_{g-1} & \mathbf{0}_{g-1, g-1} \end{pmatrix}, \\ C &= \begin{pmatrix} 1 & \mathbf{0}_{g-1}^T \\ \mathbf{0}_{g-1} & \mathbf{0}_{g-1, g-1} \end{pmatrix}, & D &= \begin{pmatrix} 0 & \mathbf{0}_{g-1}^T \\ \mathbf{0}_{g-1} & \mathbf{1}_{g-1, g-1} \end{pmatrix}, \end{aligned} \quad (1)$$

Lattice reduction

- Lattice generated by all integer combinations of the vectors t_i of T , $\mathfrak{LB} = T^T T$
- Minkowski: shortest lattice vectors which can be extended to a basis of \mathcal{L} .
- Gram-Schmidt vectors

$$t_i^* = t_i - \sum_{j=1}^{i-1} \mu_{i,j} t_j^*, \quad \mu_{i,k} = \frac{\langle t_i, t_k^* \rangle}{\|t_k^*\|^2}$$

- LLL condition

$$\|t_k^*\|^2 \geq (\delta - \mu_{k,k-1}^2) \|t_{k-1}^*\|^2 \quad (1)$$

Example

- random matrix $Y = \mathfrak{S}\mathbb{B}$

$Y =$

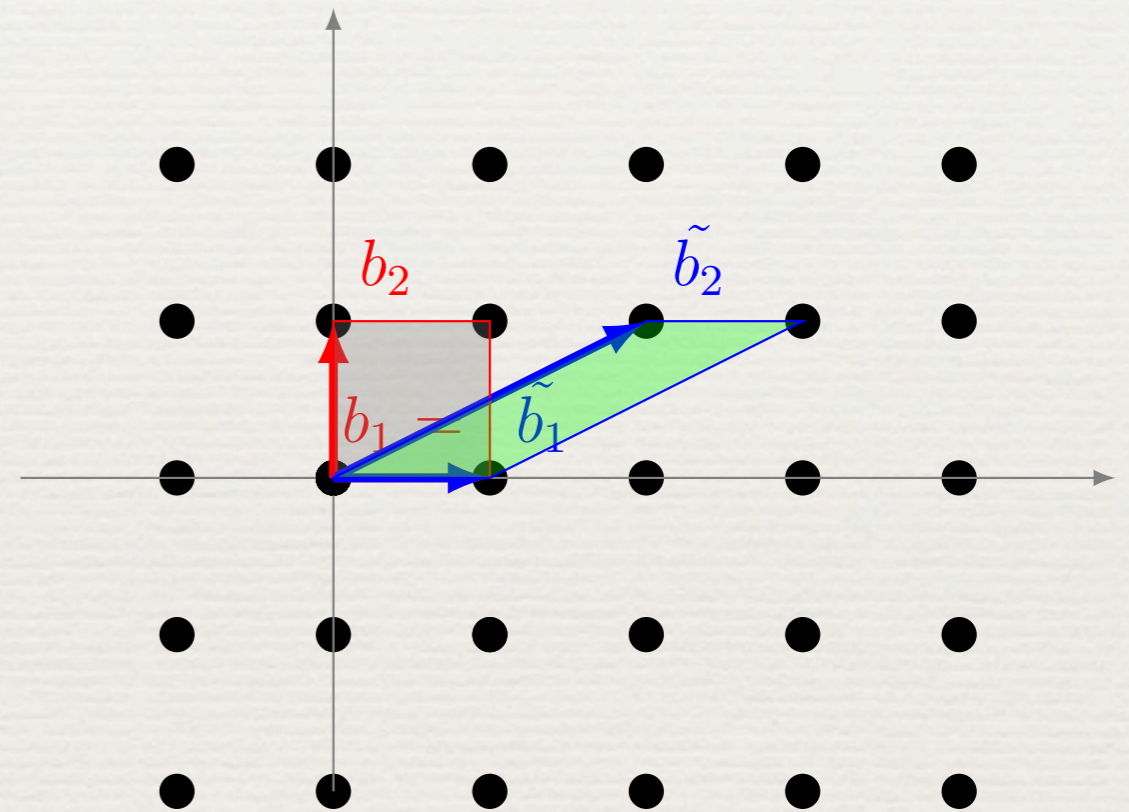
1.7472	0.5191	1.0260	0.6713
0.5191	1.3471	0.2216	-0.5122
1.0260	0.2216	0.6801	0.4419
0.6713	-0.5122	0.4419	0.7246.

- Minkowski reduction

0.2205	0.0443	0.0342	0.0351
0.0443	0.3636	0.1660	-0.0294
0.0342	0.1660	0.3688	0.1516
0.0351	-0.0294	0.1516	0.3753.

- LLL reduced matrix ($\delta = 3/4$)

0.3753	0.0294	-0.1516	0.0351
0.0294	0.3636	0.1660	-0.0443
-0.1516	0.1660	0.3688	-0.0342
0.0351	-0.0443	-0.0342	0.2205.



C. Jaber (thesis, 2017)

Davey-Stewartson equations

$$i\psi_t + \psi_{xx} - \alpha^2 \psi_{yy} + 2(\Phi + \rho |\psi|^2) \psi = 0,$$

$$\alpha = i, 1, \quad \rho = \pm 1, \quad \Phi_{xx} + \alpha^2 \Phi_{yy} + 2\rho |\psi|_{xx}^2 = 0,$$

- ♦ model the evolution of weakly nonlinear water waves traveling predominantly in one direction, wave amplitude slowly modulated in two horizontal directions, plasma physics, ...
- ♦ completely integrable, theta-functional solutions (Malanyuk 1994, Kalla 2011)
- ♦ algorithm to transform computed homology basis to 'Vinnikov' basis (K, Kalla 2011)

Trott curve

- M-curve, $g = 3$, real simple branch points ($s = (1, -1, -1)$)

$$144(x^4 + y^4) - 225(x^2 + y^2) + 350x^2y^2 + 81 = 0$$

$$\text{DS1}^+, \lambda(a) = -0.2, \lambda(b) = 0.2 \quad \alpha = i, \rho = 1$$

$$t \in [-2, 2]$$

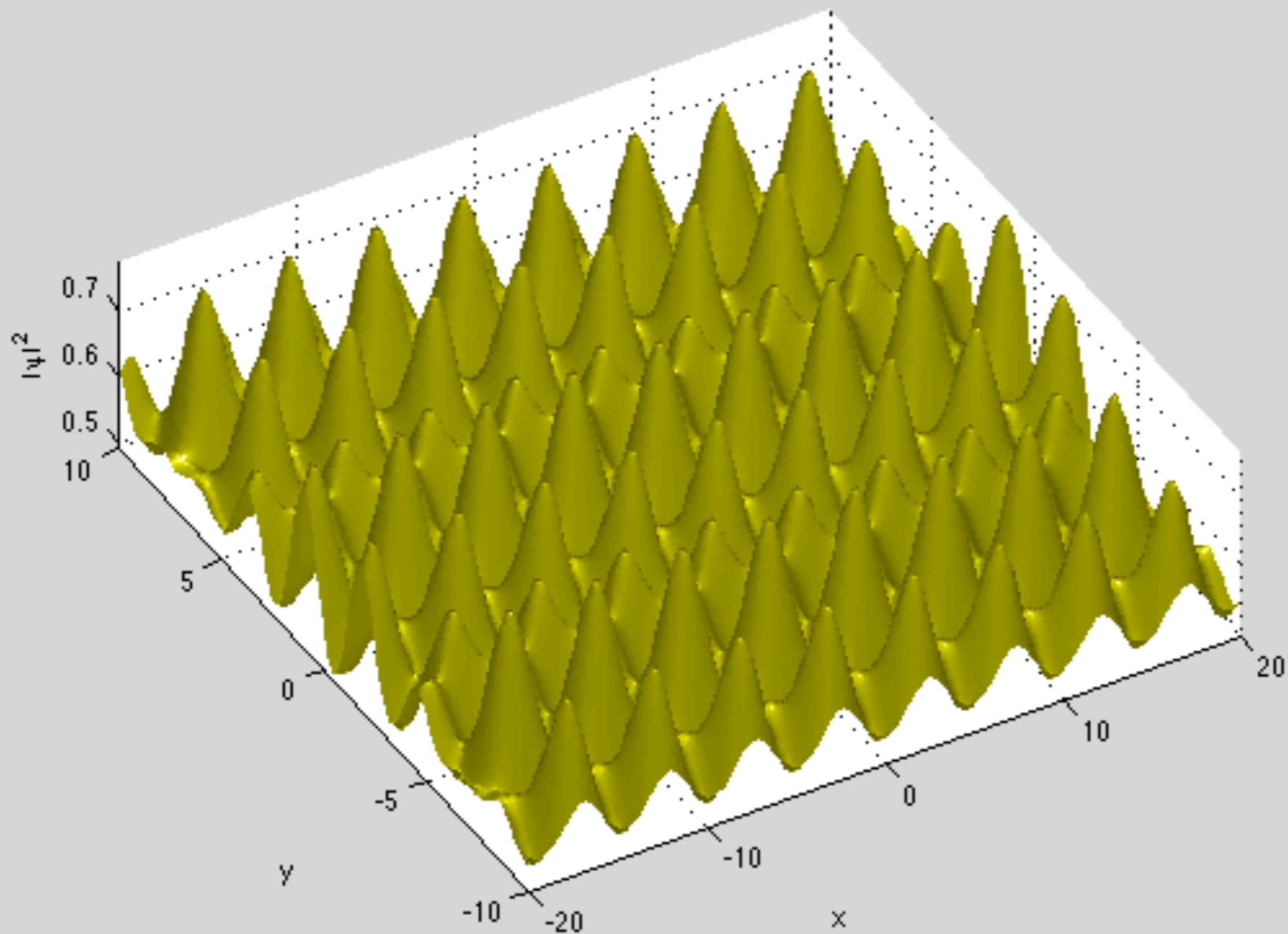
Trott curve

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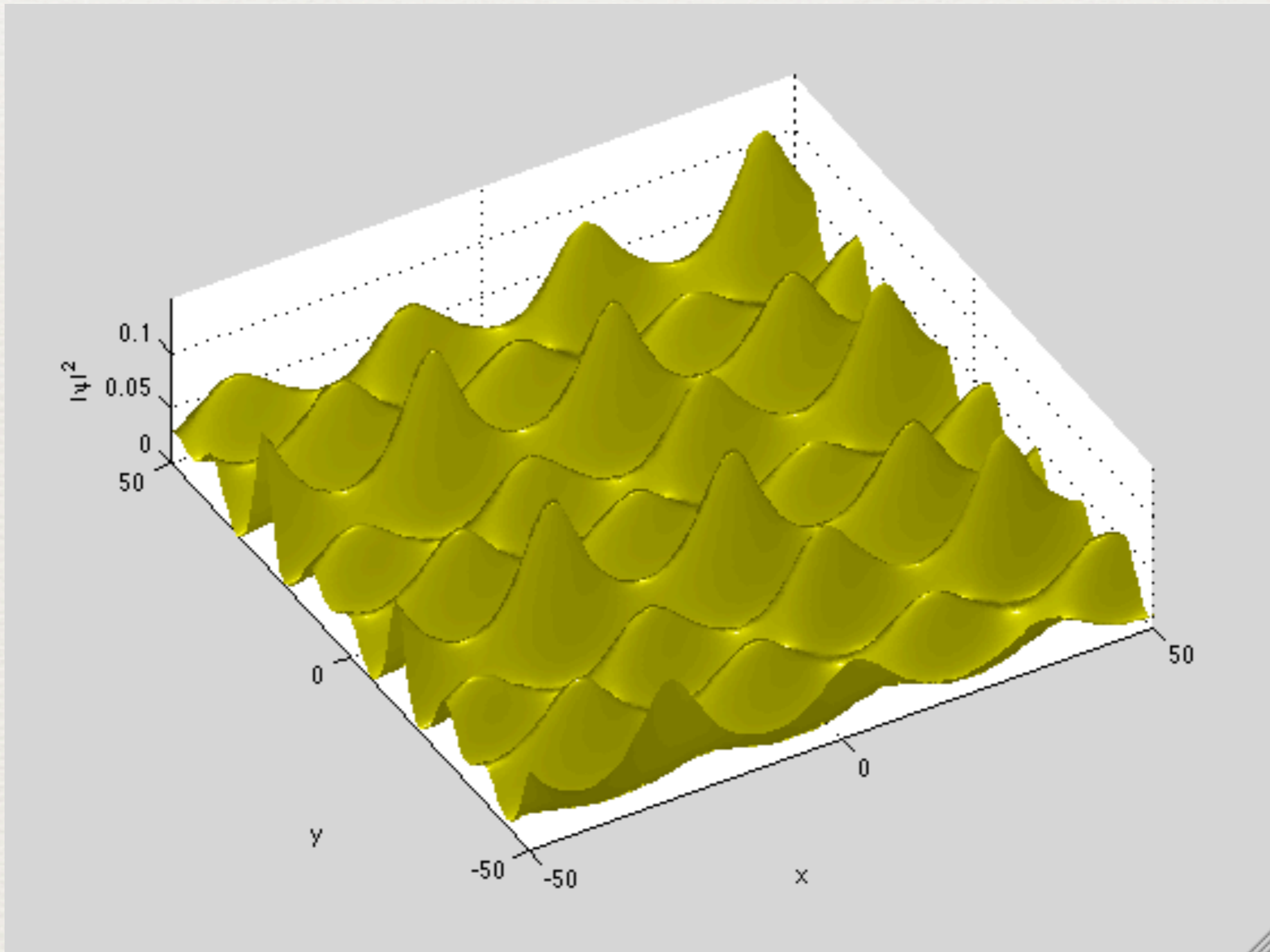


DS on Fermat curve $g=3$

$$\text{DS2-}, \lambda(a) = -1.5 + i, \lambda(a) = -1.5 - i \quad t \in [-5, 5]$$

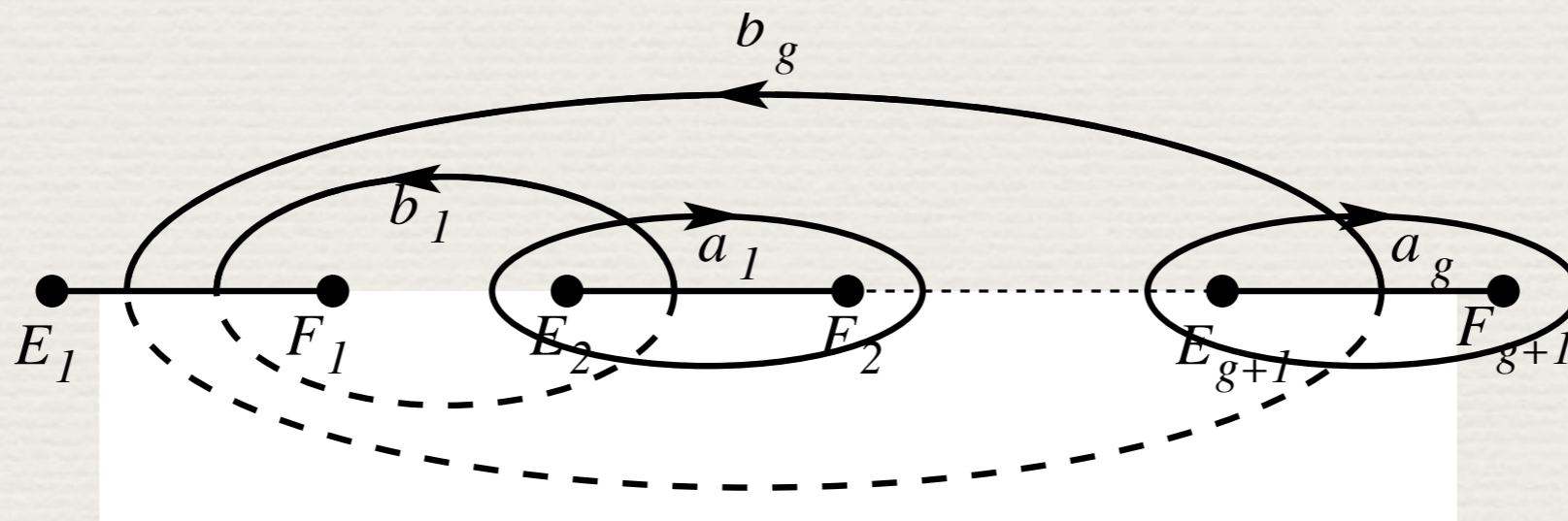
DS on Fermat curve $g=3$

DS2-, $\lambda(a) = -1.5 + i$, $\lambda(a) = -1.5 - i$ $t \in [-5, 5]$



Hyperelliptic surfaces

- ♦ general surface: analytic continuation most time consuming
- ♦ y : square root of polynomial in x , holomorphic differentials known, $y^2 + \prod_{i=1}^{2g+2} (x - x_i) = 0$
- ♦ analytic continuation of the root trivial (square root, correct unwanted sign changes)
- ♦ branch points prescribed, can almost collapse
- ♦ homology can be chosen a priori



Outlook

- ♦ more efficient determination of critical points, homotopy tracing, endgame
- ♦ Siegel transformation of the Riemann matrix to fundamental domain in genus 3
- ♦ parallelization of theta functions

Lecture Notes in Mathematics 2013

Alexander I. Bobenko
Christian Klein *Editors*

Computational Approach to Riemann Surfaces

 Springer

Urheberrechtlich geschütztes Material

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