

Quantitative weak propagation of chaos for stable-driven McKean-Vlasov SDEs

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Summer school: mean field systems

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Lévy processes

Lévy process

A \mathbb{R}^d -valued process $Z = (Z_t)_{t \geq 0}$ is a Lévy process if

- its paths are a.s. **càdlàg starting from 0**
- it has **stationary increments**, i.e. for any $0 \leq s \leq t$, $Z_t - Z_s$ has the same law as Z_{t-s}
- it has **independent increments**, i.e. for any $0 \leq t_1 \leq t_2 \leq \dots \leq t_d$, $(Z_{t_1}, Z_{t_2} - Z_{t_1}, \dots, Z_{t_d} - Z_{t_{d-1}})$ are independent.

\Leftrightarrow Lévy processes are random walks in continuous time.

Example: Brownian motion, Poisson process etc.

Lévy measure

A positive measure ν on \mathbb{R}^d is a Lévy measure if

- $\nu(\{0\}) = 0$.
- $\int_{\mathbb{R}^d} \min(1, |z|^2) d\nu(z) < +\infty$.

\rightarrow description of the jumps of Z .

Poisson random measure

Poisson random measure

A random measure \mathcal{N} on $\mathbb{R}^+ \times \mathbb{R}^d$ is a Poisson random measure with intensity $dt \otimes \nu$ if

- $\mathcal{N}([0, t] \times A) \sim \text{Poisson}(t\nu(A))$ for all measurable set A and $t \in \mathbb{R}^+$.
- For all $(A_i)_i$ measurable disjoint, $(\mathcal{N}(A_i))_i$ are independent.

If Z is a Lévy process:

$$\mathcal{N}([0, t] \times A) := \text{Card} \{s \in [0, t], \Delta Z_s := Z_s - Z_{s-} \in A\}.$$

Compensated Poisson random measure

If A is bounded from below: $\tilde{\mathcal{N}}([0, t] \times A) := \mathcal{N}([0, t] \times A) - t\nu(A)$. $\tilde{\mathcal{N}}$ is the compensated Poisson random measure \rightarrow **martingale property**.

α -stable process

α -stable process

A Lévy process Z is a α -stable process with $\alpha \in (0, 2]$ if for all $c > 0$, $(Z_{ct})_t$ has the same distribution as $(c^{\frac{1}{\alpha}} Z_t)_t$. (**Scaling property**)

- $\alpha = 2$: Brownian motion.
- Scale: Z_t acts with a typical scale of $t^{\frac{1}{\alpha}}$.
- Moments: **When $\alpha < 2$** , $\forall t, \mathbb{E}|Z_t|^\beta < +\infty \Leftrightarrow \beta \in [0, \alpha)$.
- Lévy-Itô decomposition: When $\alpha \in (1, 2)$, $Z_t = \int_0^t \int_{\mathbb{R}^d} z \tilde{\mathcal{N}}(ds, dz) \rightarrow$ **centered martingale**.
- Lévy measure: writes in polar coordinates $\nu(dz) = \lambda(d\theta) \frac{dr}{r^{1+\alpha}}$, where λ is a non-zero finite measure on the sphere \mathbb{S}^{d-1} .

Rotationally invariant α -stable process

Rotationally invariant α -stable process

A α -stable process Z is rotationally invariant if $\nu(dz) = C \frac{dz}{|z|^{d+\alpha}}$.

In the sequel, $C = 1$.

Generator: $\Delta^{\frac{\alpha}{2}}$ given by

$$\Delta^{\frac{\alpha}{2}} f(x) := \int_{\mathbb{R}^d} [f(x+z) - f(x) - \nabla f(x) \cdot z] d\nu(z), \quad x \in \mathbb{R}^d$$

→ non-local operator (**fractional Laplacian**)

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→ non-local operator (**fractional Laplacian**) defined for $f \in C_b^{1+\gamma}(\mathbb{R}^d)$ with $\gamma \in (\alpha - 1, 1]$ i.e. $f \in C_b^1(\mathbb{R}^d)$ and ∇f is γ -Hölder since

$$\int_{D_1} |z|^{1+\gamma} d\nu(z) < +\infty \Leftrightarrow \gamma \in (\alpha - 1, 1].$$

McKean-Vlasov SDEs and particle systems

Fix $T > 0$.

$$\begin{cases} dX_t = b(t, X_t, \mu_t) dt + dZ_t, & t \in [0, T], \\ \mu_t := [X_t], \\ X_0 = \xi, \quad [\xi] = \mu \in \mathcal{P}(\mathbb{R}^d), \end{cases} \quad (\text{McKean-Vlasov})$$

where

- Z rotationally invariant α -stable process with $\alpha \in (1, 2)$,
- $[\xi]$ is the distribution of ξ ,
- $b : [0, T] \times \mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}^d$ (Hölder-type assumptions on b).

Mean-field interacting particle system:

$$\begin{cases} dX_t^{i,N} = b(t, X_t^{i,N}, \bar{\mu}_t^N) dt + dZ_t^i, & t \in [0, T], i \in \{1, \dots, N\}, \\ \bar{\mu}_t^N := \frac{1}{N} \sum_{j=1}^N \delta_{X_t^{j,N}}, & (= \text{empirical measure}) \\ X_0^{i,N} = X_0^i, \end{cases} \quad (\text{Particle system})$$

where $(Z^i)_i$ and $(X_0^i)_i$ are i.i.d with the same distributions as Z and ξ .

Goal: quantitative weak propagation of chaos

Goal: Prove that $\bar{\mu}_t^N \xrightarrow{N \rightarrow \infty} \mu_t$ in distribution **with a rate** using test functions.

Quantitative weak propagation of chaos

Find explicit rates of convergence for $\mathbb{E}|\phi(\bar{\mu}_t^N) - \phi(\mu_t)|$ and $|\mathbb{E}\phi(\bar{\mu}_t^N) - \mathbb{E}\phi(\mu_t)|$, for functions $\phi : \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}$ belonging to a sufficiently large class of functions.

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Strategy: use the tools developed with **Mean-Field Games**.

↪ Strategy described in the book of Carmona and Delarue inspired by *[Mischler et.al., 2015]* and *[Cardaliaguet et.al., 2019]*.

↪ When Z is a Brownian motion, done by Chaudru de Raynal and Frikha under similar assumptions.

↪ Notion of **semigroup** crucial.

Semigroup, generator and PDE: linear case

Standard linear stable-driven SDE:

$$\begin{cases} dX_t^{s,x} = b(t, X_t^{s,x}) dt + dZ_t, & t \in [s, T], \\ X_s^{s,x} = x, \end{cases}$$

- Semigroup: For $f : \mathbb{R}^d \rightarrow \mathbb{R}$, $T_{s,t}f(x) := \mathbb{E}(f(X_t^{s,x})) \rightarrow T_{s,t} = T_{s,\tau} \circ T_{\tau,t}$. (**Markov property**)
- Generator: $L_s f(t, x) := b(s, x) \cdot \nabla f(t, x) + \Delta \frac{\alpha}{2} f(t, \cdot)(x)$. (**Itô's formula**)
- Backward Kolmogorov PDE: If b regular enough, $(s, x) \in [0, t] \times \mathbb{R}^d \mapsto T_{s,t}f(x)$ is the unique solution to the parabolic problem

$$\begin{cases} \partial_s u(s, x) + L_s u(s, \cdot)(x) = 0, & \forall (s, x) \in [0, t] \times \mathbb{R}^d, \\ u(t, \cdot) = f. \end{cases} \quad (1)$$

- Transition density: $p(s, t, x, \cdot)$ is the fundamental solution to (1) and $T_{s,t}f(x) = \int_{\mathbb{R}^d} f(y)p(s, t, x, y) dy \rightarrow$ **Smoothing properties for (1)**.

Semigroup, generator and PDE: non-linear case

What happens for (McKean-Vlasov)?

McKean-Vlasov SDE:

$$\begin{cases} dX_t^{s,\xi} = b(t, X_t^{s,\xi}, [X_t^{s,\xi}]) dt + dZ_t, & t \in [s, T], \\ X_s^{s,\xi} = \xi, & [\xi] = \mu \in \mathcal{P}(\mathbb{R}^d), \end{cases} \quad (\text{McKean-Vlasov})$$

- If (McKean-Vlasov) **well-posed**, $[X_t^{s,\xi}] =: [X_t^{s,\mu}]$ depends on ξ only through its distribution μ .
- Semigroup: For $\phi : \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}$, $\mathcal{T}_{s,t}\phi(\mu) := \phi([X_t^{s,\mu}]) \rightarrow \mathcal{T}_{s,t} = \mathcal{T}_{s,\tau} \circ \mathcal{T}_{\tau,t}$.

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- **If (McKean-Vlasov) well-posed**, $[X_t^{s,\xi}] =: [X_t^{s,\mu}]$ depends on ξ only through its distribution μ .
- Semigroup: For $\phi : \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}$, $\mathcal{T}_{s,t}\phi(\mu) := \phi([X_t^{s,\mu}]) \rightarrow \mathcal{T}_{s,t} = \mathcal{T}_{s,\tau} \circ \mathcal{T}_{\tau,t}$.
- Generator: \mathcal{L}_s should be a PDE operator acting on functions defined on the space of measures \rightarrow **differentiation of a map w.r.t. the measure + Itô's formula along a flow of measures.**
- Backward Kolmogorov PDE and transition density: **Smoothing properties ?**

Here $\mathcal{P}(\mathbb{R}^d)$ is **infinite-dimensional** while the noise Z is finite-dimensional.
 \hookrightarrow **weaker smoothing properties.**

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Differential calculus: linear derivative

$\mathcal{P}_\beta(\mathbb{R}^d)$ = space of probability measure having a finite β -moment \rightarrow Wasserstein metric.

Linear derivative

A function $u : \mathcal{P}_\beta(\mathbb{R}^d) \rightarrow \mathbb{R}$ has a linear derivative if there exists $\frac{\delta}{\delta m} u \in \mathcal{C}^0(\mathcal{P}_\beta(\mathbb{R}^d) \times \mathbb{R}^d; \mathbb{R})$ s.t.

- For all compact $\mathcal{K} \subset \mathcal{P}_\beta(\mathbb{R}^d)$, there exists $C_{\mathcal{K}} > 0$ s.t.

$$\forall \mu \in \mathcal{K}, \forall v \in \mathbb{R}^d, \left| \frac{\delta}{\delta m} u(\mu)(v) \right| \leq C_{\mathcal{K}}(1 + |v|^\beta).$$

- For all $\mu, \nu \in \mathcal{P}_\beta(\mathbb{R}^d)$

$$\lim_{h \rightarrow 0} \frac{u(\mu + h(\nu - \mu)) - u(\mu)}{h} = \int_{\mathbb{R}^d} \frac{\delta}{\delta m} u(\mu)(v) d(\mu - \nu)(v) = \left\langle \frac{\delta}{\delta m} u(\mu), \mu - \nu \right\rangle.$$

\rightarrow Gateaux derivative in the space of signed measures.

Properties and examples

Example (Linear functions): $u(\mu) = \int_{\mathbb{R}^d} \phi d\mu$ with ϕ continuous and $|\phi(x)| \leq C(1 + |x|^\beta)$ then

$$u(\mu) - u(\nu) = \int_0^1 \int_{\mathbb{R}^d} \phi(v) d(\mu - \nu)(v) d\lambda \Rightarrow \frac{\delta}{\delta m} u(\mu)(v) = \phi(v).$$

Itô's formula for (McKean-Vlasov)

Theorem (Itô's formula along a flow of probability measures)

For the solution to (McKean-Vlasov), i.e. $X_t = X_0 + \int_0^t b(s, X_s, \mu_s) ds + Z_t$ (with b bounded), we have

$$u(\mu_t) - u(\mu_0) = \int_0^t \mathcal{L}_s u(\mu_s) ds,$$

where the **generator** \mathcal{L}_s is given by

$$\begin{aligned} \mathcal{L}_s u(\mu) := & \int_{\mathbb{R}^d} \partial_v \frac{\delta}{\delta m} u(\mu)(v) \cdot b(s, v, \mu) d\mu(v) \\ & + \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \left[\frac{\delta}{\delta m} u(\mu)(v+z) - \frac{\delta}{\delta m} u(\mu)(v) - z \cdot \partial_v \frac{\delta}{\delta m} u(\mu)(v) \right] \frac{dz}{|z|^{d+\alpha}} d\mu(v). \end{aligned}$$

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- Denoting by L_s^μ the generator of the corresponding linear SDE where μ is fixed

$$\mathcal{L}_s u(\mu) = \int_{\mathbb{R}^d} L_s^\mu \frac{\delta}{\delta m} u(\mu)(v) d\mu(v).$$

- Crucial assumption:** $\partial_v \frac{\delta}{\delta m} u(\mu)(\cdot)$ γ -Hölder unif. in μ with $\gamma > \alpha - 1$.

Assumptions and example

$$\begin{cases} dX_s^{t,\xi} = b(s, X_s^{t,\xi}, [X_s^{t,\xi}]) ds + dZ_s, & s \in [t, T], \\ X_t^{t,\xi} = \xi, \quad [\xi] = \mu \in \mathcal{P}(\mathbb{R}^d), \end{cases} \quad (\text{McKean-Vlasov})$$

Assumptions:

- b jointly continuous and globally **bounded** on $[0, T] \times \mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d)$.
- For all t, μ , $b(t, \cdot, \mu)$ is η -**Hölder** on \mathbb{R}^d , for some $\eta \in (0, 1]$, unif. in t, μ .
- For all t, x , the map $b(t, x, \cdot)$ has a linear derivative s.t. $\frac{\delta}{\delta m} b(t, x, \mu)(\cdot)$ is η -**Hölder** on \mathbb{R}^d unif. in t, x, μ and $\frac{\delta}{\delta m} b$ is **bounded**.
- For any (t, x, v) , the map $\frac{\delta}{\delta m} b(t, x, \cdot)(v)$ has a linear derivative s.t. $\frac{\delta^2}{\delta m^2} b(t, x, \mu)(v, \cdot)$ is η -**Hölder** continuous unif. in t, x, μ, v and $\frac{\delta^2}{\delta m^2} b$ is **bounded**.

Example: $b(t, x, \mu) = \int_{\mathbb{R}^d} \tilde{b}(t, x, y_1, \dots, y_l) d\mu(y_1) \dots d\mu(y_l)$, with \tilde{b} η -**Hölder** w.r.t. to (x, y_1, \dots, y_l) unif. in t and **bounded**.

Theorem

The non-linear martingale problem related to (McKean-Vlasov) is well-posed, thus there exists a unique weak-solution $(X_s^{t,\mu})_{s \in [t, T]}$.

Object of interest: semigroup acting on the following space

Hölder space

Fix $\beta \in (1, \alpha)$. For $\delta \in [0, 1]$, $\mathcal{C}^{(1,\delta)}(\mathcal{P}_\beta(\mathbb{R}^d))$ is the set of functions $\phi : \mathcal{P}_\beta(\mathbb{R}^d) \rightarrow \mathbb{R}$ having a linear derivative s.t.

$$\left| \frac{\delta}{\delta m} \phi(\mu)(v_1) - \frac{\delta}{\delta m} \phi(\mu)(v_2) \right| \leq C |v_1 - v_2|^\delta.$$

For $\phi \in \mathcal{C}^{(1,\delta)}(\mathcal{P}_\beta(\mathbb{R}^d))$, we define

$$U : (t, \mu) \in [0, T] \times \mathcal{P}_\beta(\mathbb{R}^d) \mapsto \phi([X_T^{t,\mu}]).$$

Solution to the backward Kolmogorov PDE with terminal condition

Theorem

The function U belongs to $\mathcal{C}^0([0, T] \times \mathcal{P}_\beta(\mathbb{R}^d)) \cap \mathcal{C}^1([0, T] \times \mathcal{P}_\beta(\mathbb{R}^d))$ and satisfies:

$$\left| \partial_v \frac{\delta}{\delta m} U(t, \mu)(v) \right| \leq C(T - t)^{\frac{\delta-1}{\alpha}},$$

and for $\gamma \in (0, 1] \cap (0, (2\alpha - 2) \wedge (\eta + \alpha - 1))$

$$\left| \partial_v \frac{\delta}{\delta m} U(t, \mu)(v_1) - \partial_v \frac{\delta}{\delta m} U(t, \mu)(v_2) \right| \leq C(T - t)^{\frac{\delta-1-\gamma}{\alpha}} |v_1 - v_2|^\gamma.$$

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Moreover, U is the (unique) classical solution to

$$\begin{cases} \partial_t U(t, \mu) + \mathcal{L}_t U(t, \cdot)(\mu) = 0, & \forall (t, \mu) \in [0, T] \times \mathcal{P}_\beta(\mathbb{R}^d), \\ U(T, \mu) = \phi(\mu), & \forall \mu \in \mathcal{P}_\beta(\mathbb{R}^d), \end{cases}$$

where

$$\begin{aligned} \mathcal{L}_s h(\mu) := & \int_{\mathbb{R}^d} b(s, v, \mu) \cdot \partial_v \frac{\delta}{\delta m} h(\mu)(v) d\mu(v) \\ & + \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \left[\frac{\delta}{\delta m} h(\mu)(v + z) - \frac{\delta}{\delta m} h(\mu)(v) - z \cdot \partial_v \frac{\delta}{\delta m} h(\mu)(v) \right] \frac{dz}{|z|^{d+\alpha}} d\mu(v). \end{aligned}$$

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Notations

Recall that $(\mu_t)_{t \in [0, T]}$ = flow of marginal distributions of (McKean-Vlasov).

Vectorial form for the particle system: We set for $t \in [0, T]$ and $\mathbf{x} = (x_1, \dots, x_N) \in (\mathbb{R}^d)^N$

$$\mathbf{X}_t^N = \begin{pmatrix} X_t^{1,N} \\ \vdots \\ X_t^{N,N} \end{pmatrix}, \quad \mathbf{Z}_t^N = \begin{pmatrix} Z_t^1 \\ \vdots \\ Z_t^N \end{pmatrix} \quad \text{and} \quad \mathbf{b}^N(t, \mathbf{x}) := \begin{pmatrix} b(t, x_1, \bar{\mu}_x^N) \\ \vdots \\ b(t, x_N, \bar{\mu}_x^N) \end{pmatrix} \in (\mathbb{R}^d)^N$$

$$\left\{ \begin{array}{l} d\mathbf{X}_t^N = \mathbf{b}^N(t, \mathbf{X}_t^N) dt + d\mathbf{Z}_t^N, \quad t \in [0, T], \\ \mathbf{X}_0^N = \begin{pmatrix} X_0^1 \\ \vdots \\ X_0^N \end{pmatrix}. \end{array} \right.$$

The noise \mathbf{Z}^N is a cylindrical α -stable process with

- \mathcal{N}^N = Poisson random measure,
- ν^N = Lévy measure on $(\mathbb{R}^d)^N$.

Quantitative weak propagation of chaos

Recall that $\beta \in (1, \alpha)$.

Test functions

For $\delta \in (0, 1]$ and $L > 0$, $\mathcal{C}_L^{(2, \delta)}(\mathcal{P}_\beta(\mathbb{R}^d))$ is the set of functions $\phi : \mathcal{P}_\beta(\mathbb{R}^d) \rightarrow \mathbb{R}$ admitting two linear derivatives $\frac{\delta}{\delta m} \phi$ and $\frac{\delta^2}{\delta m^2} \phi$ s.t.

$$\left| \frac{\delta}{\delta m} \phi(\mu)(v_1) - \frac{\delta}{\delta m} \phi(\mu)(v_2) \right| + \left| \frac{\delta^2}{\delta m^2} \phi(\mu)(v_1, v'_1) - \frac{\delta^2}{\delta m^2} \phi(\mu)(v_2, v'_2) \right| \leq L(|v_1 - v_2|^\delta + |v'_1 - v'_2|^\delta).$$

Quantitative weak propagation of chaos

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$$\left| \frac{\delta}{\delta m} \phi(\mu)(v_1) - \frac{\delta}{\delta m} \phi(\mu)(v_2) \right| + \left| \frac{\delta^2}{\delta m^2} \phi(\mu)(v_1, v'_1) - \frac{\delta^2}{\delta m^2} \phi(\mu)(v_2, v'_2) \right| \leq L(|v_1 - v_2|^\delta + |v'_1 - v'_2|^\delta).$$

Theorem

Let us fix $\gamma \in (0, 1] \cap (0, (\delta + \alpha - 1) \wedge (2\alpha - 2) \wedge (\eta + \alpha - 1))$. There exists a positive constant $C_T = C(d, T, \alpha, \beta, \eta, \gamma, \delta, L)$ non-decreasing in T such that for all $\phi \in \mathcal{C}_L^{(2, \delta)}(\mathcal{P}_\beta(\mathbb{R}^d))$, it holds

$$\mathbb{E}|\phi(\bar{\mu}_T^N) - \phi(\mu_T)| \leq C_T \mathbb{E}W_1(\bar{\mu}_0^N, \mu_0) + \frac{C_T}{N^{1-\frac{1}{\beta}}},$$

and

$$|\mathbb{E}(\phi(\bar{\mu}_T^N) - \phi(\mu_T))| \leq \frac{C_T}{N^\gamma}.$$

Remark: For all $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ s.t. $\|\varphi\|_{\text{Lip}} \leq 1$ i.e. $|\varphi(x) - \varphi(y)| \leq |x - y|$, define

$$\phi(\mu) := \int_{\mathbb{R}^d} \varphi d\mu. \text{ Then } \phi \in \mathcal{C}_1^{(2,1)}(\mathcal{P}_\beta(\mathbb{R}^d)).$$

\hookrightarrow **Rate of convergence w.r.t. W_1 .** We have by the Kantorovich-Rubinstein theorem

$$\begin{aligned} W_1([X_T^{1,N}], \mu_T) &= \sup_{\varphi, \|\varphi\|_{\text{Lip}} \leq 1} \left| \mathbb{E} \varphi(X_T^{1,N}) - \int_{\mathbb{R}^d} \varphi d\mu_T \right| \\ &= \sup_{\varphi, \|\varphi\|_{\text{Lip}} \leq 1} \left| \mathbb{E} \int_{\mathbb{R}^d} \varphi d\bar{\mu}_T^N - \mathbb{E} \int_{\mathbb{R}^d} \varphi d\mu_T \right| \\ &= \sup_{\phi \in \mathcal{C}_1^{(2,1)}(\mathcal{P}_\beta(\mathbb{R}^d))} \left| \mathbb{E} \phi(\bar{\mu}_T^N) - \mathbb{E} \phi(\mu_T) \right| \\ &\leq \frac{C}{N^\gamma}. \end{aligned}$$

\rightarrow Allows also **non-linear functions** of the empirical measure.

Idea of the proof

- Consider $U(t, \mu) = \phi([X_T^{t, \mu}])$ the solution to the Kolmogorov PDE.
- Compare $\phi(\bar{\mu}_T^N) - \phi(\mu_T) = U(T, \bar{\mu}_T^N) - U(T, \mu_T)$ through dynamics of $t \in [0, T] \mapsto U(t, \bar{\mu}_t^N) - U(t, \mu_t)$.
- The map $t \in [0, T] \mapsto U(t, \mu_t) = \phi([X_T^{t, \mu_t}])$ is constant by the **flow property**.

Idea of the proof

- Consider $U(t, \mu) = \phi([X_T^{t, \mu}])$ the solution to the Kolmogorov PDE.
- Compare $\phi(\bar{\mu}_T^N) - \phi(\mu_T) = U(T, \bar{\mu}_T^N) - U(T, \mu_T)$ through dynamics of $t \in [0, T] \mapsto U(t, \bar{\mu}_t^N) - U(t, \mu_t)$.
- The map $t \in [0, T] \mapsto U(t, \mu_t) = \phi([X_T^{t, \mu_t}])$ is constant by the **flow property**.

→ Additional regularity on U : for $\gamma \in (0, 1] \cap (0, (2\alpha - 2) \wedge (\eta + \alpha - 1))$

$$\left| \partial_v \frac{\delta}{\delta m} U(t, \mu_1)(v_1) - \partial_v \frac{\delta}{\delta m} U(t, \mu_2)(v_2) \right| \leq C \underbrace{(T - t)^{\frac{\delta - 1 - \gamma}{\alpha}}}_{\text{integrable for } \gamma < \delta + \alpha - 1} \left(|v_1 - v_2|^\gamma + W_1^\gamma(\mu_1, \mu_2) \right).$$

Idea of the proof

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→ Apply Itô's formula for the **empirical projection** $(t, \mathbf{x}) \in [0, T] \times (\mathbb{R}^d)^N \mapsto U(t, \bar{\mu}_\mathbf{x}^N)$, where

$$\bar{\mu}_\mathbf{x}^N = \frac{1}{N} \sum_{k=1}^N \delta_{x_k} \text{ and for the particle system using that}$$

$$\partial_{x_i} U(t, \bar{\mu}_\mathbf{x}^N) = \frac{1}{N} \partial_v \frac{\delta}{\delta m} U(t, \bar{\mu}_\mathbf{x}^N)(x_i) \quad \rightarrow \text{choose } \gamma > \alpha - 1.$$

Idea of the proof

$$\begin{aligned}
& U(t, \bar{\mu}_t^N) - U(t, \mu_t) - \left(U(0, \bar{\mu}_0^N) - U(0, \mu_0) \right) \\
&= \int_0^t \partial_t U(s, \bar{\mu}_s^N) ds \\
&+ \frac{1}{N} \sum_{i=1}^N \int_0^t \partial_v \frac{\delta}{\delta m} U(s, \bar{\mu}_s^N)(X_s^{i,N}) \cdot b(s, X_s^{i,N}, \bar{\mu}_s^N) ds \\
&+ \int_0^t \int_{(\mathbb{R}^d)^N} \left[U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N + \mathbf{z}}^N) - U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) - \partial_x U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) \cdot \mathbf{z} \right] d\nu^N(\mathbf{z}) ds \\
&+ \int_0^t \int_{\{|\mathbf{z}| \geq 1\}} \left[U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N + \mathbf{z}}^N) - U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) \right] \tilde{\mathcal{N}}^N(ds, d\mathbf{z}) \\
&+ \int_0^t \int_{\{|\mathbf{z}| < 1\}} \left[U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N + \mathbf{z}}^N) - U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) \right] \tilde{\mathcal{N}}^N(ds, d\mathbf{z}) \\
&=: I_1 + I_2 + I_3 + I_4 + I_5.
\end{aligned}$$

→ **Goal:** make appear the Kolmogorov PDE.

Idea of the proof

→ Note that I_2 can be rewritten as

$$\begin{aligned} I_2 &= \frac{1}{N} \sum_{i=1}^N \int_0^t \partial_v \frac{\delta}{\delta m} U(s, \bar{\mu}_s^N)(X_s^{i,N}) \cdot b(s, v, \bar{\mu}_s^N) ds \\ &= \int_0^t \int_{\mathbb{R}^d} \partial_v \frac{\delta}{\delta m} U(s, \bar{\mu}_s^N)(v) \cdot b(s, v, \bar{\mu}_s^N) d\bar{\mu}_s^N(v) ds. \end{aligned}$$

This is one term of the PDE satisfied by U .

→ Concerning I_3 :

$$I_3 = \int_0^t \int_{(\mathbb{R}^d)^N} \left[U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N + \mathbf{z}}^N) - U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) - \partial_x U(s, \bar{\mu}_{\mathbf{x}_{s^-}^N}^N) \cdot \mathbf{z} \right] d\nu^N(\mathbf{z}) ds$$

does not appear in the PDE satisfied by U (only terms involving the linear derivative of U).

↪ **Linearisation** with the linear derivative.

Idea of the proof

Setting $m_{s,z,w}^i := w \bar{\mu}_{\mathbf{X}_{s^-}^N + \bar{z}_i}^N + (1-w) \bar{\mu}_{\mathbf{X}_{s^-}^N}^N$

$$\begin{aligned}
 I_3 &= \frac{1}{N} \sum_{i=1}^N \int_0^t \int_{\mathbb{R}^d} \int_0^1 \left[\frac{\delta}{\delta m} U(s, m_{s,z,w}^i)(\mathbf{X}_{s^-}^{i,N} + z) \right. \\
 &\quad \left. - \frac{\delta}{\delta m} U(s, m_{s,z,w}^i)(\mathbf{X}_{s^-}^{i,N}) - \partial_\nu \frac{\delta}{\delta m} U(s, \bar{\mu}_{\mathbf{X}_{s^-}^N}^N)(\mathbf{X}_{s^-}^{i,N}) \cdot z \right] dw d\nu(z) ds, \\
 &= \int_0^t \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \left[\frac{\delta}{\delta m} U(s, \bar{\mu}_{s^-}^N)(x+z) - \frac{\delta}{\delta m} U(s, \bar{\mu}_{s^-}^N)(x) \right. \\
 &\quad \left. - \partial_\nu \frac{\delta}{\delta m} U(s, \bar{\mu}_{s^-}^N)(x) \cdot z \right] d\nu(z) d\bar{\mu}_{s^-}^N(x) ds \\
 &\quad + \text{Error term.}
 \end{aligned}$$

↪ Allows to use the PDE satisfied by U .

Idea of the proof

Using the PDE, it remains

$$\begin{aligned}
 & U(t, \bar{\mu}_t^N) - U(t, \mu_t) - (U(0, \bar{\mu}_0^N) - U(0, \mu_0)) \\
 &= \text{Error term} \\
 &+ \int_0^t \int_{\{|z| \geq 1\}} \left[U(s, \bar{\mu}_{\mathbf{X}_{s^-}^N + z}^N) - U(s, \bar{\mu}_{\mathbf{X}_{s^-}^N}^N) \right] \tilde{\mathcal{N}}^N(ds, dz) \\
 &+ \int_0^t \int_{\{|z| < 1\}} \left[U(s, \bar{\mu}_{\mathbf{X}_{s^-}^N + z}^N) - U(s, \bar{\mu}_{\mathbf{X}_{s^-}^N}^N) \right] \tilde{\mathcal{N}}^N(ds, dz) \\
 &= \text{Error term} + I_4 + I_5.
 \end{aligned}$$

- Use **martingale property**/**BDG's inequalities** for I_4 and I_5 .
- Find upper-bounds for each term using **the bounds/Hölder controls** on the derivatives w.r.t. the measure of $U \rightarrow$ **time-integrability of the singularities**.
- Conclude using the continuity of U that

$$U(t, \bar{\mu}_t^N) - U(t, \mu_t) \xrightarrow[t \rightarrow T]{} U(T, \bar{\mu}_T^N) - U(T, \mu_T) = \phi(\bar{\mu}_T^N) - \phi(\mu_T) \quad \text{a.s.}$$

THANK YOU FOR YOUR ATTENTION !

References:

- *Itô's formula for the flow of measures of Poisson stochastic integrals and applications*, T.C. 2022.
- *Quantitative weak propagation of chaos for stable-driven McKean-Vlasov SDEs*, T.C. 2022.